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AMSAT Telemetry Decoder Manual

1 Introduction

Thank you for downloading the Fox Telemetry Decoder. You can use this program to demodulate, store and analyze telemetry data from many of AMSAT's spacecraft. We hope that you will also upload the telemetry you receive to the AMSAT server so that it can be used by other scientists, students and our research partners, whose experiments fly on our satellites.

FoxTelem is experimental. We are sure it can be improved. Please provide feedback and suggestions by email to <u>g0kla@arrl.net</u> or by logging an issue at <u>https://github.com/ac2cz/FoxTelem/issues</u>

AMSAT has launched several spacecraft based on the FOX-1 architecture and will launch more in the future based similar architectures, such as the Linear Transponder (LTM) and GOLF. When satellites are launched, they are assigned an OSCAR (Orbital Satellite Carrying Amateur Radio) number. After launch that number is used for tracking and dissemination of Keplerian Elements (Keps), also called Two Line Elements (TLEs). If you decide to have FoxTelem calculate the position of the spacecraft, then you will need to make sure that the name in FoxTelem is the same as the name in the TLEs.

Fox-ID	Name in this document	Name Post Launch	Status
	and at Launch		
1	Fox-1A	AO-85	End of mission
2	RadFxSat / Fox-1B	AO-91	End of mission
3	Fox-1Cliff	AO-95	Telemetry Only
4	Fox-1D	AO-92	End of mission
5	RadFxSat2 / Fox-1E	AO-109	Difficult to copy
8	Golf-T	-	Future launch

Here are some examples of the spacecraft that FoxTelem supports:

In addition to the Fox-1 spacecraft, the AMSAT-NA Linear Transponder Module (LTM), Internal Housekeeping Unit (IHU) and BPSK Modulator is being leveraged by university partners directly in their spacecraft. This uses a BPSK format to transmit telemetry to earth. HuskySat was the first such partnership. It was launched November 2, 2019, was operational for several months and completed numerous experiments that the University had scheduled.

Fox-ID	Spacecraft owner	Name in this document and	Name Post Launch	Status
		at Launch		
6	University Of Washington	HuskySat	HO-107	End of Mission



You can also create your own spacecraft for experiments here on earth, assuming you transmit the same FSK or BPSK format. A good example of this is the CubeSatSimulator which has two spacecraft for use with the hardware that they provide. (See the AMSAT FoxTelem Designers Handbook for details of the design process).

Fox-ID	Spacecraft owner	Name in this document and at	Name Post Launch	Status
7	CubesatSim.org	CubeSatSim-FSK	N/A	Operational
99	CubesatSim.org	CubeSatSim-BPSK	N/A	Operational

In FoxTelem 1.08 and later you can assign a display name to label the spacecraft on tabs and graphs. For example, if you set the name to AO-91 to match the Keplerian elements in the file you receive, you can also set the display name to RadFxSat. Then tabs and graphs for Fox-ID 2 will have that title.

Satellites decoded by FoxTelem support multiple telemetry formats. Here is a partial list, additional formats can be added using configuration files. (See the AMSAT FoxTelem Designers Handbook for details):

- **FSK 200bps (Fox1):** Data Under Voice (DUV) is 200 bps Frequency Shift Keying (FSK) data sent at the same time as the transponder audio. Whenever the FM transmitter is on, data is being sent. This happens during beacons and during live QSOs.
- **FSK 9600bps (Fox1):** High Speed is 9600 bps FSK sent instead of the transponder. This is used for data intensive experiments such as the Virginia Tech Camera on Fox-1D (AO-92) and University of Iowa HERCI experiment on Fox-1D (AO-92). On Fox-1A (AO-85) high speed was only used to test the functionality. This mode is only active when commanded from the ground. You can recognize High Speed because it sounds like an old school computer modem.
- **BPSK 1200bps (Fox1E):** is 1200 bps Binary Phase Shift Keying (BPSK) data sent alongside a linear transponder. This provides continuous real time telemetry and whole orbit data. This was also used for HuskySat-1
- BPSK 1200bps (LTM): is an updated 1200 bps BPSK format.

FoxTelem will receive and store the formats assuming you can feed it clean audio or IQ signals from a hardware Software Defined Radio (SDR).

1.1 License

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3 Getting Started

3.1 Installing

FoxTelem is supplied as an archive file (.zip on windows and gzip on Linux/macOS). You can unzip the contents and put it in the directory of your choice. Right on the desktop works well, as does somewhere in your home directory or documents directory. If you install it into the macOS Applications folder or into the Windows "Program Files" folder, then make sure you choose a different directory to write the decoded data into. You can do this the first time you run the program and is a good practice for all installs, because later upgrades are then easier.

3.2 Running for the first time

Run FoxTelem by double clicking FoxTelem.exe on Windows. On macOS or Linux, you should be able to double click the FoxTelem start script. If that does not work, then run the script from the command line.

When FoxTelem starts you should have the Welcome screen shown below (unless you passed the logfile directory as a command line parameter). We recommend you choose a logfile directory that is different to the location of the program.

Welcome to the Amsat Fox Telemetry Analysis Tool			
	AMSAT Fox Satellite Decoder		
It looks like this is the first time you have Also note that configuration settings will If you want to run multiple copies of Fox logFile directory name as a paramater.	e run the FoxTelem program. You must choose a director be saved in: C:\Users\chris\.FoxTelem (Telem, using different settings, then hit cancel and rerun Otherwise choose a logFile directory below. See the ma	y to store the the decode passing the nual for details.	d data.
Log files directory		Browse	
	Continue Cancel		

Once FoxTelem starts it will tell you that "No spacecraft are loaded". You can add the spacecraft that you want to decode using the Spacecraft > Add menu option.



AMSAT 1	Felemetry Analysis Tool				_		\times
File Decoder	r Spacecraft Help						
Input							
Source Start	Telem Format: Select audio source here th	FSK 200bps (Fox 1) v	✓ ● AF	⊖ıq	Spacecraft Tracke No spacecraft loa Use the spacecra to add a satellite.	ded. ft menu	
Output	Silence Speaker	center / Switch modes	~		Audio Options View Filtered A Monitor Filtered Squelch when	Audio ed Audio no teleme	etry
	Sam	ple rate:			Eye Diagra - 0.0 5	ım VR	
. .				ļ	Errors 0 Erasi	ures O	
Version 1.12z	- 13 Sep 2022 Logs: C:\Use	rs\chri SDR Errors: 0 / 0	Audio missed	: 0.0% / 0	Frames: 0 Payloads:	0 Queu	e: 0 / 0

Feel free to just add one to get started. You can later add or remove spacecraft files from the Spacecraft menu. A master copy of each spacecraft file is stored in the spacecraft subdirectory of the installation folder.

If you are going to run one copy of FoxTelem then you can install all the spacecraft you want to be able to decode. If you are running multiple copies of FoxTelem then just select the spacecraft required for the copy you are setting up.



3.3 Testing with a wav file

To confirm everything is working you can download a test wav file for AO-85 (Fox-1A) from <u>amsat.us/FoxTelem/recordings</u>. A recording ending in AF is audio as received from a radio. A recording ending in RF is an IQ file.

Select "Load Wav File" from the FoxTelem "File" menu and navigate to the directory where you saved the file.

Then press the "Start" button.

The file will play through the decoder and the audio waveform will be shown together with an eye diagram. You should get a number of frames decoded.



There should be data visible on the AO-85

satellite tab. If the data is difficult to read because the font is too large or too small then open the settings screen from the File menu and change the font size for the Health Modules.

Note that FoxTelem will try to play the recording at the right speed. This is important if you want FoxTelem to follow an IQ signal. If you select "Fast Playback" then it will play through very quickly. This is usually fine for AF recordings. Note also that it will always process at normal speed if you monitor the Audio. This will force FoxTelem to play the audio back through your speakers and will slow down the playback to normal speed.

3.4 Launching one or more copies of FoxTelem

You can run FoxTelem in two different ways. In Option 1, you use one copy of FoxTelem that decodes all the satellites you want to track. In Option 2, you run multiple copies of FoxTelem that each track different satellites. Broadly speaking if you use one radio or a single SDR you will probably run one copy of FoxTelem. If you use multiple radios, soundcards or SDRs then you will use multiple copies of FoxTelem.

There are Pros and Cons to these two approaches, which can be summarized below:

Running a Single Copy

Run FoxTelem by double clicking FoxTelem.exe on Windows. On macOS or Linux, you should be able to double click the foxtelem start script. You may also be able to double click the FoxTelem.jar file, but this can be unreliable on different versions of Unix because the current directory is not always set to the Jar file directory.



When running a single copy:

Pros:

One copy of FoxTelem stores its settings in a central place. It uses one logfile directory to store the decoded telemetry from all spacecraft. All spacecraft decoders share the same audio input or device. It's simple to understand and configure.

Cons:

You cannot decode two spacecraft at the same time. You can't use two radios or two SDRs. The "Find Signal" algorithm may not work as well when multiple satellites are being tracked as it needs to check each in turn.

Running Multiple Copies

Run FoxTelem from a script or batch file or from a short cut.

On Windows this is easiest with a short cut. Create one as follows:

- 1. Right click on the FoxTelem.exe file and select "Create Shortcut". You can also right click and drag FoxTelem.exe out to another folder or your desktop. When you release the mouse button "Create Shortcut" is presented as an option.
- 2. Right Click on the short cut and select "Properties".
- 3. Now go to explorer and find or create the directory you want to use for log files. This will also be where the configuration gets stored.
- 4. Click in the box at the top of the explorer window that displays the folder path and it will highlight it. Type Ctrl-C to copy it.
- 5. Go back to the shortcut properties window and put your cursor in the "Target" text field. This contains the full path to FoxTelem.exe. Insert a space at the end then paste the path to the logfile directory with Ctrl-v.
- 6. Click OK.
- 7. Move the short cut to your desktop or where you would like to have it. Double clicking this shortcut will now run FoxTelem with this logfiles directory and a unique set of Configuration.

On Mac or Linux create a new bash shell script. Name it something like FoxTelem_AO-85. In the script put:

```
#!/bin/bash
<path-to-foxtelem-install-dir>/foxtelem <path-to-logfile-dir>
```

Note that this is running the start script rather than the jar file. You can run the jar file directly if you want, but you need to make sure that you cd to the installation directory before running "java -jar FoxTelem.jar".

Make this script executable with chmod +x FoxTelem_AO-85. You should be able to run FoxTelem with this script.

When running multiple copies: Pros:



You can decode from two spacecraft at the same time. You can use FoxTelem to read audio from as many audio inputs or devices as you like, such as a 2m radio and a 70cm radio, or two different SDRs on the same or different bands.

Cons:

You can not decode from two bands with a single SDR. With multiple copies of FoxTelem listening to the same SDR you need to keep each copy on the same band. To decode from two bands you need to use two different SDRs.

You need to pass a command line parameter to FoxTelem when you run it, so it knows which logfile directory you want it to use. The configuration and decoded spacecraft data are stored in different logfile directories, so you need to configure each. It is more complicated than running a single copy.

3.5 Troubleshooting Issues running FoxTelem

FoxTelem will not start if you do not have java installed, FoxTelem 1.04 requires Java version 6 (sometimes called 1.6) and FoxTelem 1.05 and later requires Java version 8. You will get a message from the launcher telling you to download and install the latest version. We recommend installing the latest LTS (Long Term Support) version of Java distributed by the Eclipse Foundation through their site <u>https://adoptium.net/</u>. As of 2022, that is version 11 or version 17.

If you get an error message from Windows SmartScreen like the below, then click "More Info" and then "Run Anyway". Windows gives this message for new or little known applications that have not established a reputation.



Similarly, macOS has security precautions and they have changed in recent releases. It may be a message like the below. It may also say that FoxTelem is dangerous, corrupt, or not runnable.



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FoxTelem is not really damaged, and it can in fact be opened. The easiest way to fix it is to right click (which would be two-finger click on a touch pad or magic mouse) and select "run" from the menu. You will get a similar message, but one of the choices is "run anyway". After you do that the first time, you should not need to again. The message is displayed because your "Security and Privacy" settings do not allow applications that are not installed from the Mac App Store. That is a good setting to have, but if the "right click / two-finger click" option does not work then you will need to temporarily change your Security and Privacy settings. Change them back after you have run FoxTelem. It should run the next time without changing the settings.

If you are on Windows and the program complains that it is missing MSVCR100.dll or something similar to that, then you need to install the Microsoft Visual C++ redistributable: For 32 bit Windows: <u>http://www.microsoft.com/download/en/details.aspx?id=5555</u> For 64 bit Windows: <u>http://www.microsoft.com/download/en/details.aspx?id=14632</u>

If you do not know if you have 32 or 64 bit Windows then on Windows 10 or 11 right click the start menu and select System.

On Windows 7 Open "System" by clicking the *Start* button, right-clicking *Computer*, and then clicking *Properties*. Under *System*, you can view the system type.

If FoxTelem still won't start, then see the troubleshooting section at the end of the manual, ask for help on the amsat-bb mailing list (<u>https://mailman.amsat.org/hyperkitty/list/amsat-bb@amsat.org/</u>) or email <u>g0kla@arrl.net</u>



4 Decoding

The telemetry for a Fox-1 FM spacecraft is sent in two different ways. During all beacons and while the transponder is on, low speed telemetry is sent on the same frequency, even while the transponder is in use. At certain times the transponder may be commanded off and high speed data mode may be in use.

The telemetry for Fox-1E and any other AMSAT spacecraft with a linear transponder will be 1200 bps Phase Shift Keying (PSK).

These three modes are described in the following sections.

4.1 FSK 200bps (Fox1 DUV)

This is sent as Data Under Voice (DUV) in the audio band from 0 to 200Hz in the same FM channel as the transponder audio. While a QSO is in progress, we can receive telemetry from the spacecraft.

This makes certain demands on the ground station. There should be no high pass filtering of the FM audio. Ideally the band from 0 to 200Hz is untouched when it is received from the telemetry decoder. Unfortunately, this is not the case for almost all radios.

What we want to receive is something like below. You can see all of the bits, although there is some "ringing" from filtering in the decoder itself. The eye diagram shows the last set of bits received, drawn one on top of another. We can see a nice shape and it fits into the sample window. The bits are sampled vertically at the midpoint, with the signal to noise shown by the red line. We want a signal to noise ratio of at least 3dB. Higher is better. 2dB is marginal. 10dB is excellent. We also see the Error rate in the Eye Diagram window. This is updated each time we receive a frame from the satellite and shows the number of bytes that were corrected by the <u>Reed Solomon</u> (RS) Decoder (Errors) and the number of bytes that were invalid 8b10b words (Erasures).



4.2 FSK 9600bps (Fox1 High Speed Data)

High speed data is sent at 9600 bits per second Frequency Shift Keying (FSK). This is not the same format as G3RUH or other packet modes. It incorporates robust Forward Error Correction (FEC) and cannot be decoded with a hardware or software TNC.



High speed data puts even further demands on the ground station. Some radios may work through the 9600 bps data port, but best results will be obtained with a Software Defined Radio (SDR).

In High Speed Mode we want to receive a bit pattern and eye diagram like the below. Note that the bits are represented by far fewer samples and the eye diagram is now angular. The bit Signal To Noise ratio it typically lower for the same RF signal level. This means that a stronger signal (or a bigger antenna) is needed to decode high speed data. Like DUV, the errors and erasures from the RS Decoder are shown. Each high speed frame has 21 RS code words, which can each correct up to 32 errors, so the values can become quite high. This is Forward Error Correction in action and the reason you can't use a Packet TNC.



4.3 BPSK 1200bps – Binary Phase Shift Keying

Fox-1E will fly with a linear transponder. Freed from the requirement to use Frequency Modulation the telemetry data will be sent with Phase Shift Keying due to its superior performance compared to FSK. For example, the Costas Loop decoder, together with the coding gain we obtain from Forward Error Correction (FEC), can decode PSK when it is only 2-3dB above the noise. FSK needs a much stronger signal.

PSK data does not have the strict filtering requirements that DUV and High Speed Data mode require from the radio receiver. It should decode from a single sideband radio or your favorite SDR. The radio needs to be close enough to the signal for the decoder to find it. The decoder searches about 2kHz above and below the tune point to locate the data. It should be possible to tune the radio or an SDR with Doppler prediction and then let FoxTelem handle the fine tuning to decode the data.

FoxTelem supports two PSK decoders as an experiment. They are referred to as the BPSK Costas (or Costas Loop) decoder and the BPSK Dot Product (DP) decoder. Feel free to use either and report back your results. Testing on the ground with simulated data has indicated that both work well in different situations. Read the research here: <u>http://www.g0kla.com/workbench/2019-03-09.php</u>. With that said testing with HuskySat-1 showed that the Dot Product decoder was usually superior for real signals from space. For that reason, the Dot Product decoder is the default. If you want to use the Costas Loop decoder then you can select it from the File > Setting window, where it is one of the decoder options:



De	coder Options
	Upload to Server
	Find Signal
	Store FCD Params
V	Use Left Stereo Channel
	Swap IQ
	PSK: Use Costas

Examples of the two BPSK decoders are shown below. The details of these displays are explained in "Getting Better Decodes" later in this manual.

FoxTelem decoding with a Dot Product BPSK Decoder



FoxTelem decoding with a Costas Loop BPSK Decoder



FoxTelem 1.12 also supports multiple different Frame layouts that the BPSK decoder can decode. You select which frame layout you want to decode on the main Source screen using the pull down combo box. BPSK 1200bps (LTM) is shown selected below:

Source		Telem Format:	BPSK 1200bps (LTM)	~	
	Start	RTL SDR	~	0.960 MHz ${\scriptstyle\bigtriangledown}$	€ IQ



If you want to automatically switch between different decoders and formats, you can setup the default decoder for each spacecraft on the Spacecraft settings screen. This is used by the "Automatic Mode Switching" algorithm described later in this manual.

4.4 Selecting a source

FoxTelem decodes audio, but there are many ways to source it. On the Input tab you select the source in the pull down box near the top, just to the right of the "start" button. One approach is to pick one of your sound cards and then feed audio into that sound card from a radio.

In the example below FoxTelem is reading from the "Primary Sound Capture" source, it will process 200bps FSK (Data Under Voice) with a 48000 bits per second sample rate. (This must be the sample rate that the sound card has and FoxTelem needs to match it. You can't change the sample rate that FoxTelem runs at without changing the sample rate of the audio that it receives.) Finally, it is expecting normal audio (AF) from a radio.

Source		Telem Format:	FSK 200bps (Fox1)	`	~			
	Start	Primary Sound Captu	ire Driver	\sim	48000	\sim	● AF	⊖ iq

FoxTelem can also read IQ audio and act as a Software Defined Radio (SDR). You do this by selecting a source that supplies In Phase audio on one stereo channel and Quadrature audio on the other. You set the correct sample rate and you choose IQ, rather than AF (to the right of the sample rate pull down). If the device is the FUNcube Dongle or the RTL-SDR then you should also be able to set the frequency directly. If it is another device, then you will need an external program to control it. FoxTelem will just read the IQ audio.

On some Mac Computers, FoxTelem may only read from the default device (this is likely a bug that I need to fix). You can select the default device from System Preferences>Sound then select Input and set the device you want as the sound input.

If you are not seeing any sound card devices on the Mac, then you may have the sample rate set to a level where no sound cards are supported. Try setting it to 48000. If you no longer have a sample rate pull down, then you need to delete the foxtelem.properties file as a work around. This is a known issue.

4.5 Setting up the levels

You may need to adjust the sound levels in your operating system. I had to adjust the levels in Windows. In Windows 10 type "Control Panel" at the start menu. From the control panel I selected: Hardware and Sound> Manage Audio Devices> and then adjusted the properties for the sound card on the Custom and Levels tabs.



Control P ► H	ardware and Sound 🔸 🔹 🍫 Search Control Panel 🔎	Sound Sound Sound Sounds Communications Sounds Communications Sounds Communications	×
Control Panel Home System and Security Network and Internet • Hardware and Sound Programs User Accounts and Family Safety Appearance and Personalization Clock, Language, and Region Ease of Access	Devices and Printers Add a device Add a printer Add a Bluetooth device Mouse Device Manager With the settings for media or devices Play CDs or other media automatically Sound Adjust system volume Change system sounds Monage audio devices Power Options Change power-saving settings Change what the power buttons do Require a password when the computer wakes Change when the computer sleeps Choose a power plan Display Make text and other items large or smaller Adjust screen resolution Connect to an external display How to correct monitor flicker (refresh rate) NVIDIA Control Panel	Select a recording device below to modify its settings:	e nce Appy
	Intel® Ranid Storage Technology	-	

On the Custom tab I unchecked AGC and on the Levels tab I set it to 50. You may have other settings for your sound card.

To set the levels correctly in FoxTelem, uncheck the "View Filtered Audio", shown below on the right, and make sure that the signal is visible but does not take up more than a quarter to a half of the display. If it is too low, you won't decode frames, if it is too high you will see it square off on the display. The exact setting is not critical because FoxTelem has some AGC built in. Too high a level is more of a danger than too low. Also note that the white noise when there is no FM signal is usually much louder, which is to be expected. This may well drive the decoder into distortion. A quiet transponder, which has been keyed, but which has no audio signals in it, should not distort. The spacecraft will still be transmitting telemetry and you can decode it.



Also note that the sample rate is shown on the Advanced tab (in the Windows example screens). Windows typically defaults it to 44100 and the decoder defaults to 48000. Your Operating System may default to something else. The sample rate in the sound card setup needs to be the same as the



sound card sample rate in the decoder or you will get a poor decode rate. The Source Selection image above shows the sound card rate near the top.

Why do we default FoxTelem to 48000 if Windows defaults to 44100? Because 44100 does not work as well. 9600 bits per second, 1200 bits per second and 200 bits per second all divide equally into 48000. This means fewer corrections to keep the clock in sync and a better decode rate.

4.6 Feeding the Audio

You can wire a cable from the data out port of your radio to both stereo channels of a 3.5mm plug and connected it to the sound card. Select the widest audio bandwidth that you can, because we want a response down to nearly DC. Usually this is a 9600 baud packet setting or a direct feed from the FM discriminator. I got the best results by modifying my FT-736R to feed audio from the discriminator, but my FT-817 was also able to decode Fox without modification, using the 9600 baud data output port.

The results from most radios are workable but not ideal. The audio below is from the FT-817. Note the shape of the bits. This is characteristic of high pass filtering, even though I am using the data port. The bits start at their full value then steeply slope.



The frequency spectrum shows a null below 20Hz and the FT-817 seems to decode about 10% fewer frames than the modified FT-736R.





With that said, many stations are using radios very successfully, with some of our highest contributors using a TS-2000 exclusively.

4.7 Decoding from an IQ source such as the FUNcube Dongle

A software defined radio is a good choice because we get no filtering of the low frequency audio. The FUNcube Dongle, for example, can receive the telemetry and pass the IQ baseband audio untouched to FoxTelem.

You have two choices to set this up. Either receive the audio in your favorite SDR software and feed the demodulated audio to the telemetry decoder or use the IQ demodulation in the telemetry decoder itself. Both should work. Here are the advantages and disadvantages of using FoxTelem's IQ demodulator:

Advantages

- FoxTelem will find the satellites signal when it appears and will follow the Doppler. You do not need a separate application to set the frequency.
- FoxTelem will setup default filters and settings that are optimal for the telemetry formats
- FoxTelem will measure several parameters about the received signal such as Signal to noise ratio.
- You don't need to use another piece of software, such as Virtual Audio Cable, to connect the two programs. Or feed the audio out of the computer and back in again with a physical cable.

Disadvantages

- A separate SDR program may have better capabilities than the SDR in the Telemetry Decoder.
- Your existing SDR may already be configured to work with Doppler correction software and the rest of your ground station
- FoxTelem can be more compute-intensive than some other SDR programs and may not work as well on slower computers

In either case, you should receive bits that are something like the image below in "Starting the Decoder" (which is using the IQ demodulation in the decoder and shows the Frequency spectrum).



4.8 Starting the decoder

The start button kicks off the decoder and FoxTelem reads audio from the audio source that you selected. If this is audio from a separate SDR program such as SDR# or HDSDR then make sure the AF radio button is selected and the sample rate is the same as your sound card or SDR/Virtual Cable. If it is IQ audio from the FUNcube Dongle or another SDR, then make sure that the IQ radio button is selected.



If you are receiving from an SDR like the FUNcube Dongle then setting the frequency will change the frequency that the dongle is tuned to and set the correct filters. For some SDRs, you will need to use a separate control program to set the frequency and any filters. In both cases, the frequency will be the center frequency of the displayed RF spectrum. This is not the frequency that you are receiving, which is shown by the black vertical line. FoxTelem will measure the receiver frequency by calculating the offset from the center. You should avoid decoding the satellite in the center of the spectrum because it will be distorted by a noise spike that sits in the middle.



4.9 Finding the Satellite's Signal in FoxTelem's SDR

You can monitor several satellites in FoxTelem. For example, if you are using the SDR in FoxTelem (IQ Mode) with the center frequency set to 145940.000 and 192kHz of spectrum is available, then Fox-1A (AO-85), RadFxSat (AO-91), Fox-1Cliff and Fox-1D (AO-92) can all be monitored.

What happens though if one spacecraft is transmitting on 435750.00 while the others are on 2 meters? Or if one spacecraft is transmitting with PSK while the others are using FSK? For that you will want to review "Automatically Retune / Switch Modes, in the section below this. This section focuses on the algorithms for finding the spacecraft signal itself.

4.9.1 Tracking spacecraft

The first step is to enable or disable tracking of a given Spacecraft. You can do this by clicking on them in the list to the top right of the Input Screen. Below we see AO-85 and AO-91 tracked, while AO-92 is not tracked. In the example below FoxTelem is calculating their position (which is setup on the File > Settings window – check the box that says "FoxTelem calculates Position"). It then shows the Azimuth and Elevation. Clicking on the Blue or Grey text will toggle tracking on/off.

Spacecraft Tracked				
1/AO-85	192.6 -44.6			
2/AO-91	262.6 -44.5			
3/AO-92	Not Tracked			
Auto Start				

Notice also that there is a priority order for the spacecraft which determines which will tune the FoxTelem SDR if two spacecraft are in the sky at the same time. You set the priority on the Spacecraft screen from the Spacecraft menu, near the top.

Spacecraft paramaters					
Identification					
Name (for Keps)	AO-85	ID: 1	Priority 1 $$		

Now FoxTelem will track this spacecraft before others with a higher number.

NO TLE?

If you have a message in the tracking window that says No TLE, then it means FoxTelem can not find the Two Line Elements or Keplerian Elements (Keps) for this spacecraft. You probably don't have the name setup correctly. It needs to match the name of the spacecraft in the nasabare.txt file that FoxTelem downloads from

Spacecraf	t Tracked
1/AO-85	Tracked / No TLE
	Auto Start

AMSAT's website. You can change the Name (for Keps) on the Spacecraft screen from the spacecraft menu. In the example above it says AO-85.



With that said, there are two option for the actual tracking:

- **Find Signal:** Search for the signal based on appearance of a characteristic signal in the expected frequency range. Follow the signal and record its frequency while decoding the data.
- Calculate Doppler and decode the signal at the predicted frequency

Why are there two options? Good question. We will explain below, first covering Find Signal and then Calculate Doppler. And in fact, there are three options, because you can disable both. Though this is likely only useful in the lab.

4.9.2 Find Signal

For a new user it is easiest just to click Find Signal and let FoxTelem take care of things. It also allows a researcher to measure the signal characteristics more easily. You don't have to worry if the Doppler calculation is inaccurate, perhaps because the spacecraft oscillator has significant thermal drift or you forgot to update the TLEs. Even the downlink frequency and tracking bands can be loosely defined. Find Signal will still work. You enable Find Signal on the File > Settings Panel, in the Decoder Options.

The image below shows FoxTelem tracking Fox-1D / AO-92 with a High Speed Signal. Even though this is noisy, we can see the characteristic shape of the High Speed telemetry. Note that SNR is checked bottom left, so the value just above the signal is the Signal to Noise Ratio. Also note that the search range shown by the purple bars is the search for the center of the signal. It is the range that the tune point will search. The signal can extend outside the search range as long as the center of the signal remains inside it. These bars are the frequencies defined on the Spacecraft screen and are called Lower Freq Bound and Upper Freq Bound.





In fact, there is a trick to setting the search range. Once you have some data at your ground station, open the Measurements Tab for the spacecraft and look at the "Carrier Frequency" that FoxTelem has been logging. This is a log of the tune point in FoxTelem's SDR for each frame that you have received. If you click on the value and plot a graph, you can see the classic s shape of the Doppler curve for a single pass. You can also look at a long period and see the maximum and minimum frequencies. Use these as a guide to set the search range. But do not set it too tight as long term thermal drift causes the nominal spacecraft frequency to change over time. Once you have enough data, you will also be able to see that on the measurements tab.

When FoxTelem finds a signal in the expected frequency range, it checks to see if it contains valid satellite telemetry. If it does, then it pauses the scan and decodes the data in the normal way. You can see in the image above that "Decode" is displayed in the top right of the Frequency Spectrum window.

If the signal is lost then FoxTelem waits 2 minutes before resuming the scan. It will display "Faded" during this wait. This is just longer than the period between beacons and will allow FoxTelem to track a pass when the satellite is in Safe Mode or when the transponder is not in use.

After 2 minutes, if no signal is received, then FoxTelem assumes the pass is over and scanning is resumed. Parameters such as Time of Closest Approach (TCA) are calculated at the end of a pass. You will see 1 frame held in the server queue until the pass is considered complete because the TCA and frequency at TCA are added to that frame before it is sent to the AMSAT server.

Find Signal can be further refined as follows:

- Setting "when peak over X dB" to a value will fine tune when FoxTelem jumps to a signal to test it. If you have interference in the pass band then you may want to set this higher to avoid scanning them. If you have a clear passband but the spacecraft is often weak, you may want to set it lower. This value is the same as the value displayed beside a signal when "Show Peak" is checked
- When FoxTelem has switched to a signal it then confirms that the "SNR is over Y dB". This is the average signal to noise and is the same as the value shown beside a signal when "Show SNR" is checked.
- If the Average Signal to Noise ratio is high enough then FoxTelem checks the Signal to Noise Ratio of the bit stream. This is the SNR value shown in the eye diagram. If it is above the third threshold then it decides that this is a signal from a Fox satellite and locks onto it

4.9.3 Calculate Doppler

Find Signal can miss frames when there is fading or when we are in beacon mode. It is also incompatible with the automatic center frequency retuning and automatic mode switching. BPSK decoding with Find Signal can be problematic due to the tight requirements to follow the frequency and phase. If you are getting frustrated with Find Signal then accurate tracking of the Doppler may be the best approach. I say "may" because there are plenty of things to get wrong with Doppler tracking and you may get less decodes than Find Signal. But when properly setup the results are usually better.



You enable Doppler calculation on the File > Settings screen bottom left. Toggle "FoxTelem Calculates Doppler" on. Note that it is dependent on "FoxTelem Calculates Position" being on and that in turn requires that you have defined your ground stations position.

If FoxTelem calculates Doppler, then it will download the latest TLEs in the background and will tune the SDR. But it does not know how accurate your SDR hardware is or what frequency the spacecraft telemetry is actually on. It almost certainly is not precisely the frequency published by AMSAT and will vary over time. Advanced users will tweak the SDR and downlink frequency on a periodic basis to maximize performance.

With Doppler calculation on, the frequency delta from the nominal downlink frequency is displayed alongside the tracking information for the spacecraft. Now we have Azimuth, Elevation and Doppler shift.

Spacecraf	t Tracked
1/AO-85	214.4 -62.4 +1.188kHz
2/AO-91	228.0 -53.5 +0.752kHz
3/AO-92	165.9 -64.9 +1.040kHz
	Auto Start

If the Doppler tracking is inaccurate then make sure your SDR is calibrated. Try listening to a known signal and adjust the center frequency until it is precise. You can set the center frequency to the nearest Hz by specifying decimals in the center frequency box.

If your SDR is calibrated and the calculation is still not accurate, then make sure you have the best downlink frequency of the spacecraft. This is not exactly the published frequency, but will be close. It is slightly off due to thermal characteristics of the small spacecraft. If in doubt monitor it over time and adjust. Advanced users could run another copy of FoxTelem in parallel with "Find Signal" enabled so that it logs the actual downlink frequency for analysis.

Confirm that FoxTelem has downloaded the latest TLEs (Keps) into the spacecraft directory. You should be calculating the same Doppler offset as another prediction program like SatPC32, assuming they have the same TLEs. FoxTelem uses the Two Line Elements (TLEs) from nasabare.txt and downloads them automatically from amsat.org. You need to make sure that the name of the spacecraft in FoxTelem is the same as the name in nasabare.txt. In FoxTelem the "Keps name" is setup from the Spacecraft menu. Note that this can be different from the displayed name on the GUI.

You can review nasabare.txt at this url: www.amsat.org/amsat/ftp/keps/current/nasabare.txt

4.10 Automatically retune / switch modes

In some situations, you may want a single copy of FoxTelem to automatically retune the center frequency of the SDR, or switch modes between PSK and FSK, as different spacecraft pass over your



ground station. This can be useful when FoxTelem's SDR is being used or when reading audio from a real radio and the mode needs to be switched.

This option is enabled in the center of the Source Panel on the input tab. Below we see FoxTelem in AF mode and that the "Auto Switch Modes" option is grayed out.

Source		Telem Format: FSK 200bps (Fe	ox1) 🗸	
	Start	Line 1 (Virtual Audio Cable)	✓ 192000 ∨	
		Auto Switch	Modes	

In AF or IQ mode the "Auto Switch Modes" option is only available if FoxTelem knows when the spacecraft is above the horizon. It will also be greyed out if Find Signal is enabled and Auto Start is off. Therefore Auto Start must be selected if you want to use Find Signal and have the Freq / Mode switched automatically. It is incompatible with continuously running "Find Signal" because the mode would be constantly switched as each Spacecraft is checked.

For FoxTelem to know when a spacecraft is above the horizon either "FoxTelem calculates position" or "Read Position from SatPC32" need to be enabled on the settings window.

When Auto Switch modes is enabled then FoxTelem will attempt to switch the decoder mode when the spacecraft rises over your ground station and the mode is wrong. If two spacecraft are above the horizon then the mode is changed to the highest priority spacecraft.

You can adjust the priority of a spacecraft and the mode that will be set from the Spacecraft settings window. For example to change the details for AO-85, go to to the menu Spacecraft > AO-85 and change the priority or mode on the screen that opens up. The screen clipping below shows AO-85 with Priority 1 and the default mode of FSK 200 bps, which is Data Under Voice (DUV).

Identification		
Name (for Keps) AO-85 ID: 1	Priority 1 🗸	
Display Name AO-85		
Fixed Paramaters	Frequency and T	racking
Model: Flight Model	Mode	FSK 200bps (Fox 1) $\qquad \lor$
Experiment 1: Vanderbilt VUC	Downlink Frea (kHz)	145980.0

Additionally, if using the FoxTelem SDR (IQ mode) then "Retune center / Switch modes" will be shown in the middle of the Source panel on the Input tab.

Sourc	e	Telem Format:	FSK 200bp	os (Fox1)	\sim		
[Start	Line 1 (Virtual Audio Cat	ole)	~	192000 🗸		● IQ
	Cente	er Frequency 145960.0	kHz	Retune	e center / Swi	tch mode:	s

When "Retune center / Switch modes" is enabled then FoxTelem will attempt to retune the SDR in addition to switching the decoder mode, when the spacecraft rises over your ground station. The center frequency will be retuned if the spacecraft's downlink frequency is outside the usable portion of the SDR band. Again, if two spacecraft are above the horizon then this is subject to the priority that you have set for the spacecraft.

4.11 Auto Start (When Above Horizon)

From Version 1.05 you can pause the decoder between satellite passes to minimize the amount of processing power needed. This is particularly important if multiple copies of FoxTelem are being run.

Note that this setting has no relation to tracking, retuning or mode switching. It is simply an option to save CPU by pausing the FoxTelem SDR and Decoder between passes. It does nothing else.

Spacecraf	t Tracked
0/AO-95	169.8 -63.9 +1.490kHz
1/AO-85	26.6 -46.7 +1.623kHz
	Auto Start

You enable this mode by checking the "Auto Start" checkbox on the Input tab or "Auto Start When above horizon" on the Settings screen. This option is only available if FoxTelem knows when the Spacecraft is above the horizon. You can use "FoxTelem calculates position" or, if you are running under Windows and would prefer to use SatPC32 to determine if the satellite is up, then you can check "Read position from SatPC32".

For this to work the name of the satellite needs to be the same as the name in nasabare.txt, if FoxTelem is calculating, or in SatPC32 if that is making the calculations. You can change the name in FoxTelem on the Spacecraft screen from the spacecraft menu. In SatPC32 you can temporarily test the connection using Auxiliary Files>DivOptions.SQF. In that file you set Line #2 to +. This will cause SatPC32 to constantly output DDE data and FoxTelem will believe that the spacecraft is above the horizon. However, you can not leave SatPC32 in that mode or FoxTelem will assume the satellite is permanently above the horizon.



4.12 NCO – The Numerically Controlled Oscillator

From FoxTelem 1.07 the SDR now defaults to a Numerically Controlled Oscillator (NCO). This is a discrete version of a VFO and is mixed with the IQ data stream to create the baseband signals. The filtering is performed with Polyphase filters that also handle the decimation. This is a cleaner down conversion than the original FFT filter design and is able to support wider bandwidth SDRs. If you are interested in how this works then you can read about it here:

https://www.g0kla.com/sdr/index.php

4.13 Starting the decoder at launch

If the decoder is running when you stop FoxTelem, then it will be running when you start FoxTelem again. This allows you to start FoxTelem from another program or have FoxTelem automatically start when the Operating System boots. You can find instructions online to add FoxTelem to the boot sequence and to configure the BIOS so that your computer automatically restarts after a power failure. You may also need to configure windows to automatically login.

4.14 Counting Frames and Payloads

In the bottom right of the Window you can see three totals, Frames, Payloads and Queued. These need a little bit of explanation.

Audio missed: 0.0% / 0 Frames: 2 Payloads: 77 Queue: 0

Frames counts the number of frames that have been received from all spacecraft since the program was restarted. This is very useful for testing, but not for much else. You can see how many frames you have decoded since you changed settings and you can compare two copies of FoxTelem side by side. You can also use this to compare against the number of frames that are reported by the AMSAT server, since it also counts frames and not payloads.

Payloads is a summary of all of the payloads that are stored in FoxTelem's database. If you add up the totals on all of the sub-tabs, then it will equal back to this number. It does not include the measurements that you have taken locally. It is also worth remembering that payloads and frames are not the same thing. A high speed frame contains many payloads, for example.

Queued is the number of frames that are waiting to be sent to the AMSAT server. If you have a fast internet connection then you may not see anything in this field. If it increases steadily and does not go down then you may not be connected to the internet or the AMSAT server may be down temporarily. You will also see 1 record held in the queue if you are using find signal. This final record contains a measurement of the Time of Closest Approach (TCA) and is sent to AMSAT. FoxTelem waits until the pass is over (or until no signal is received for 2 mins) before sending this record.

5 Fox Telemetry Format

5.1 FSK 200bps Data Under Voice

During Safe Mode beacons, when the voice announcement says, "Fox X, Safe Mode", during Transponder beacons, when the announcement says "Hi, this is Amateur Radio satellite Fox X" and



when the transponder is on, data is being sent to the ground. This is 200 bps data sent in the sub audible band.

DUV data is transmitted in a Frame with a Header, Payload and a set of Forward Error Correction (FEC) bytes. The header contains 6 bytes of data and holds the Fox id for the spacecraft, the reset (number of times the computer has rebooted), the uptime in seconds since the last reboot and the type of payload.

There are 4 types of DUV payload, each 58 bytes in length. Type 1 payloads contain real time telemetry values from the spacecraft. Type 2/3 contain the maximum and minimum values of the real time telemetry. Type 4 payloads contain 58 bytes of experiment data and vary depending on the experiments that the spacecraft is carrying. On Fox-1A (AO-85) this contains data from the Vanderbilt University Low Energy Proton experiment, which is measuring the effect of radiation on non-space rated (COTS) memory chips.

The FEC trailer contains 32 check bytes and allows us to correct significant errors due to fading or noise.

It takes the spacecraft 4.85 seconds to send a DUV frame (10 bits for the sync word, 960 bits of data, at 200 bps). We receive 2 frames in each beacon and 12 frames per minute in transponder mode. The beacon frames alternate between Real Time Telemetry and Max/Min Payloads. The transponder sends telemetry and experiment payloads in an alternating pattern of frames.

5.2 FSK 9600bps High Speed Telemetry

High speed telemetry is sent at 9600 bps. Each High Speed frame also takes about 5 seconds to send, but they contain a lot more data. The High Speed frame contains a header with the Fox id for the spacecraft, the reset (number of times the computer has rebooted) and the uptime in seconds since the last reboot. The header is followed by Type 1, Type 2 and Type 3 telemetry payloads.

The rest of the high speed frame contains experiment data and varies by spacecraft, as described below:

Fox-1A (AO-85)

In Fox-1A this is data from the Vanderbilt Radiation experiment and was intended as a test of high speed data for later spacecraft. This testing is now finished and the mission is complete. There is no intention to turn this on again.

For historical reference it was designed to download data from the experiment's buffer, which contains stored readings over many orbits. The number of type 4 payloads included in the high speed frame was variable, but typically 16 - 30. When a high speed frame was decoded you saw a big jump in the number of payloads on the radiation tab and in the footer (beside the word Decoded). The number of frames queued for upload or the number of frames you saw on the Telemetry Leaderboard were only increment by one, so for high speed they do not equal the number of payloads decoded.

Fox-1B (AO-91)



Fox-1B has the same high speed capabilities as Fox-1A. Given high speed is now already tested, there is no intention to turn on high speed data. FoxTelem does not need to be set in Auto Mode and can be left in DUV for this spacecraft,

Fox-1D (AO-92)

Fox-1D has two high speed data modes, Camera and HERCI.

In Camera mode pictures are continuously downlinked to the ground line by line from Virginia Tech's student camera experiment. Even if a single ground station only receives a few lines, the server assembles all of the received lines into an image for all to see.

HERCI mode downloaded experiment data from the University of Iowa's student radiation experiment. This mission is now complete and there is no intention to switch on HERCI mode again. The High Energy Radiation Cubesat Instrument was designed to survey the radiation environment that Fox-1D passed through.

6 Sending Data to the Server

You can help the research of students at participating Universities and contribute to the design and build of future AMSAT satellites by sending your received telemetry frames to the AMSAT server.

To send data first open the Setting screen from the File menu. Select the checkbox labeled "Upload to Server". You then need to supply your Amateur Radio callsign or some other unique identifier (e.g., "Kilowatt County Elementary School"). The identifier can also have an optional additional identifier so KA2UPW is valid, but so is KA2UPW-9 (indicating a second station this callsign is using to also collect telemetry) or something like KA2UPW-FM13 (this is indicating a grid square where the station is collecting telemetry).



×

Settings

Files and Dir	ectories					
Home directory	C:\Users\chris\.FoxTelem					
Server Data URL	https://www.amsat.org/tlm					
Log files directory	C:\Users\chris\Desktop\Test\MAN_TEST Browse					
Ground Stati	ion Params		Decoder Options			
Groundstation Nam	e	GOKLA	Upload to Server			
Primary Server		tlm.amsat.org	Store FCD Params Use Left Stereo Channel			
Secondary Server		tlm.amsat.us				
	Locator from Lat Lo	ng: IO91tp	PSK: Use 12 kHz IF			
Lat (S is -ve)		51.64583	Debug Options Enable Logging			
Long (W is -ve)		-0.375	Debug Frames Debug Fields			
Altitude (m)		0	Debug Camera Frames Debug Bits			
RF-Receiver Descri	iption	NONE	Debug Bytes Debug Values			
Formatting			Use RS FEC			
Health Module Fon	t Size	12	Use RS Erasures			
Graph Font Size		12	Debug RS Debug missed audio			
Measureme	nts □ Log Fre □ Read p ☑ FoxTele ☑ FoxTele ☑ Auto S	eq from SatPC32 in AF mode osition from SatPC32 em Calculates Position em Calculates Doppler tart Decoder when above horizo	Debug audio levels Debug Find Signal Debug (Calc) Doppler Continually Use Native File Chooser DUV Frame Length: 960 bits HS Frame Length: 52720 bits			
		Save	Cancel			

You also need to supply latitude and longitude of your ground station. This calculates the grid square that you are in as a check. Or you can enter the 6 digit maidenhead grid square and lat-long is calculated for you. Note that is slightly less precise that entering your actual latitude and longitude.



7 Downloading data from the Server

All of the data sent to the AMSAT server is available for your analysis. You can download a local copy from the File > Fetch Server Data menu option. Select the spacecraft you want to download. The server data can be quite large. For example, the downloaded file for AO-85 is approaching 100MB. Only download the spacecraft that you want to analyze. Then a minimal amount of data is transferred.

Download	Download Server Data		
Select all	Clear		
	AO-85 AO-91 AO-92 AO-95 Husky		
	Download	Cancel	

Once you click download, this will warn you that your data will be overwritten. You should use a different logfile directory from your live captured data. Section 3.2, Launching FoxTelem, describes how to setup multiple decoders. You can use this approach to have a different "decoder" for Server Data. Create a script, shortcut or batch file to launch FoxTelem. Pass it the logfile directory where you want to store the server data. When you use that script, shortcut or batch file FoxTelem will be started with the logfile directory already set to the server data directory. Any changes you make to layout, graphs, or other settings will not impact your live decoder that you use to collect telemetry. When you "Fetch Server Data" it will be safely stored in a directory separate to your own collected telemetry.

8 Understanding the Data

8.1 Fox Health Screen

The health screen shows the latest real time values received from the spacecraft at your ground station. It also shows the latest Maximum and Minimum values. You can access previous values by clicking RT, MAX or MIN at the bottom left of the window. This will open a list of historical records. You can then click on a telemetry row in the table at the bottom of the screen to see the values in the top section. You can scroll through the data using the arrow keys and the values will be displayed in the top section.



Eila Da	AT Telemetry	Analysis Tool									-		×
The Der	coder Spac	cecraft Help	10.05	II.									
Input	A0-05	A0-91 A0-92	AU-95	Husky									
Cotollite	VU Rad (1A) Measurements	ANEDO	NDER						Talamatru Da	vleede	Deee	dadı 24
Latest I	e AO-85(F Realtime:	Resets: 608	Uptime	NDER 1466067	Max: Res	sets: 608 l	Jptime: 14659	970	Min: R	esets: 608 Uptin	yioads ne: 146	0eco 6028	ded: 31
				Computer									
				Temperature (C)	RT MIN 55.5 35.5	MAX 58.2							
Radio	0			Spacecraft Spin (rpn Battery I2C	n) 0.0 0.0 FAIL	-0.0							
RX Te	mperature (C	RT MIN) 31.5 14.0	MAX 33.3	PSU1 I2C PSU2 I2C	OK OK	- B	attery		MAY	PSU	RT	MIN	MAX
RSSI (TX Ant	(dBm) tenna	-115.9 -135.5 Deployed	-65.0	Ground Resets Diagnostic Info	1 Gyro1Z (dps): 0.	.565 Ce	II A + B + C (V)	3.91 3.73	4.45	Current (mA) Board Temp (C)	6.3 32.2	5.6 16.4	980.2 34.9
RX Ant	tenna	Deployed		Hard Error Soft Error	wd 0 ec 1 mr 0 n dac 156 i2c 28 s	nf Diagnostic	Data on IHU Per	formance click	for graph	right-click for Earth	Plot		
				Safe Mode Auto Safe Mode	FALSE FALSE								
				Auto Safe Allowed	TRUE								
Expe	riments			+X Panel	RT MIN	MAX	Y Panel	RT MIN	MAX	-+Z Panel	RT	MIN	MAX
Vander	rbilt Radiation	RT MIN OK	MAX	Temp (C) Voltage (V)	0.7 -30.2 1.2 0.0	39.3 Te 5.6 Vo	mp (C) Itage (V)	2.8 -25.2 1.5 0.0	38.8 4.9	Temp (C) Voltage (V)	2.7 3.9	-26.6 0.0	57.3 4.6
				Rotation (dps)	0.7 -0.8	1.4 Ro	tation (dps)	0.5 -0.7	1.4	Rotation (dps)	1.1	0.1	1.6
		-A Paner		RT MIN MAX	-T Panel	RT	MIN MAX	-Z Panel		RT MIN MAX			
		Temp (C) Voltage (V)		-0.8 -29.9 39.8 1.5 0.0 5.4	Temp (C) Voltage (V)	0.7	-28.8 37.9 0.0 5.5	Temp (C) Voltage (V)		-0.5 -30.6 43.6 1.4 0.0 5.5			
 Current 	nt ORT O	MAX O MIN 🗆	Display Ra	w Values 🗹 Display U	TC Time				Last 18	30 samples Ca	ptured: 2	020/11/2	7 02:50:10
Version 1.	.09n - 25 Nov 20	020 Logs: C:\Use	rs\chris\De	sktop\Test\DEV1					Audio missed	: 0.0% / 0 Frames: 2 P	ayloads: 2	189773	Queue: 0 / 0
S AME	AT Telemetry	Analysis Tool											
File Dec	coder Spac	ecraft Help											
Input	AO-85	AO-91 AO-92	AO-95	Husky									
Health	VU Rad (1A)) Measurements											
Satellite													
	e AO-85(F	M) Mode: TR	ANSPO	NDER						Telemetry Pa	yloads	Deco	ded: 31
Historic	e AO-85(F al Realtin	M) Mode: TRA	ANSPO 608 Upt	NDER time: 1465965	Max: F	Resets: 608	Uptime: 146	65856	Min:	Telemetry Pa Resets: 608 Upt	iyloads ime: 14	Deco	ded: 31
Historic	e AO-85(F <mark>al Re</mark> altin	M) Mode:TR/ ne: Resets:6	ANSPO	NDER time: 1465965	Max: F	Resets: 608	Uptime: 146	65856	Min:	Telemetry Pa Resets: 608 Upt	iyloads ime: 14	Deco	ded: 31
Historic	e AO-85(F <mark>:al Re</mark> altin	M) Mode: TR/ ne: Resets:6	ANSPO	NDER time: 1465965 Computer Temperature (C) Spacecraft Spin (rpn	Max: F RT MIN 55.5 35.5 n) 0.0 0.0	MAX 58.2 -0.0	Uptime: 14	65856	Min:	Telemetry Pa Resets: 608 Upt	iyloads ime: 14	Deco	ded: 31
Historic Radio	e AO-85(F al Realtin	M) Mode:TRA ne: Resets:6 RT MIN	ANSPO	NDER time: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery I2C PSU112C	Max: F RT MIN 55.5 36.5 n) 0.0 0.0 FAIL OK	MAX 58.2 -0.0	Uptime: 146	55856	Min:	Telemetry Pa Resets: 608 Upt PSU	ime: 14	Deco	ded: 31
Radio RX Ter RSSI (i	AO-85(F cal Realtin mperature (C) dBm)	M) Mode: TRA ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5	ANSPO 608 Upt MAX 33.3 -65.0	NDER time: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery I2C PSU1 I2C PSU2 I2C Ground Resets	Max: F RT MIN 55.5 35.5 n) 0.0 0.0 FAIL OK OK 1	Resets: 608 MAX 58.2 -0.0	Uptime: 14	85856 RT MIN	Min:	Telemetry Pa Resets: 608 Upt - PSU - Current (mA)	iyloads ime: 14 RT 6.1	65915 65915 MIN 5.6	ded: 31 MAX 980.2
Radio RX Ter RSSI (1 TX Ant RX Ant	AO-85(F cal Realtin mperature (C) dBm) enna tenna	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed	ANSPO 608 Upt MAX 33.3 -65.0	NDER ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery i/2 PSU1 i2C PSU2 i2C Ground Resets Diagnostic Info Hard Error	RT MIN 55.5 35.5 0.0 0.0 FAIL OK OK OK OK 0 Count: 27 wd 0 ec 1 mr 0 n	Resets: 608 MAX 58.2 -0.0 nf 0 tn	tuptime: 14€ attery ⊪A + B + C (V)	RT MIN 3.94 3.73	Min: MAX 4.45	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C)	nyloads ime: 14 RT 6.1 32.5	MIN 5.6 16.4	MAX 980.2 34.9
Fradio RX Ter RSSI ((TX Ant RX Ant	AO-85(F cal Realtin mperature (C) dBm) enna tenna	M) Mode: TR. ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed	ANSPO 508 Upt MAX 33.3 -65.0	NDER time: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery /2C PSU1 12C PSU1 12C PSU2 12C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Safe Mode	RT MIN 55.5 35.5 n) 0.0 FAIL OK OK Count: 27 wd 0 ec 1 mr 0 n dac 156 i2c 28 s FALSE FALSE	Resets: 608 58.2 -0.0 api 0 m	Uptime: 144 attery III A + B + C (V)	85856 RT MIN 3.94 3.73	Min: MAX 4.45	Telemetry Pa Resets: 608 Upt - PSU - Current (mA) Board Temp (C)	ryloads ime: 14 RT 6.1 32.5	MIN 5.6 16.4	ded: 31 MAX 980.2 34.9
- Radio RX Ter RSSI (i TX Ant RX Ant	AO-85(F cal Realtin mperature (C) dBm) enna lenna	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed	ANSPO 608 Upt MAX 33.3 -65.0	NDER time: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery I2C PSU112C PSU12C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Safe Mode Auto Safe Allowed	RT MIN 85.5 35.5 00 0.0 FAIL OK 0K 0 0C 0.0 FAIL OK 0K 0 1 Count: 27 wd 0 ec 1 mr 0 n dac 156 l2c 28 e FALSE FALSE TRUE FALSE	Resets: 600 MAX 58.2 -0.0 mf 0 tn	Uptime: 144 attery III A + B + C (V)	RT MIN 3.94 3.73	Min: MAX 4.45	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C)	ryloads ime: 14 RT 6.1 32.5	MIN 5.6 16.4	ded: 31 MAX 980.2 34.9
Radio RX Ter RSSI (i TX Ant RX Ant	a AO-85(F cal Realtin mperature (C) dBm) enna tenna	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed	ANSPO 608 Upt 33.3 -65.0	NDER time: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery 12C PSU1 12C PSU2 12C SU2 12C Ground Resets Diagnostic Info Hard Error Safe Mode Auto Safe Mode Auto Safe Allowed +X Panel	RT MIN 55.5 35.5 0.0 0.0 FAIL OK 0K 1 Count: 27 wd 0 ec 1 nm 0 n dac 156 152 28 s FALSE FALSE FALSE TRUE TRUE	Resets: 608 58.2 -0.0 nf0 tn spi 0 m	t Uptime: 144 attery II A + B + C (V)	RT MIN 3.94 3.73	Min: MAX 4.45	Telemetry Pa Resets: 608 Upt PSU Current (mA) Board Temp (C)	ryloads ime: 14 RT 6.1 32.5	MIN 5.6 16.4	ded: 31 MAX 980.2 34.9
- Radio RX Ter RSSI (TX Ant RX Ant	a AO-85(F ail Realtin mperature (C) dBm) eena tenna	M) Mode: TR. ne: Resets: 6 RT MIN 31.7 14.0 -111.4 -135.5 Deployed Deployed RT MIN	MAX 33.3 -65.0	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery i2C PSU1 i2C PSU1 i2C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Safe Mode Auto Safe Mode	Max: F RT MIN 55.5 35.5 0.0 0.0 FAIL OK OK 0.0 dac 156 izc 28 s FALSE FALSE FALSE TRUE RT MIN 4.2 -30.2	MAX 608 MAX 58.2 -0.0 -B opi 0 m -B MAX 39.3	Uptime: 146 attery ill A + B + C (V) Y Panel mp (C)	RT MIN 3.94 3.73 RT MIN 6.2 -25.2	Min: MAX 4.45 MAX 38.8	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) -+2 Panel Temp (C)	RT 6.1 32.5 RT 5.3	EDECO 65915 5.6 16.4 MIN -26.6	ded: 31 MAX 980.2 34.9 MAX 57.3
-Radio RX Ter RSSI ((TX Ant RX Ant -Exper Vander	A AO-85(F al Realtin mperature (C) dBm) enna riments	M) Mode: TRJ ne: Resets: 6 RT MIN 31.7 14.0 -111.4 -135.5 Deployed Deployed Deployed RT MIN OK	MAX 33.3 -65.0	NDER ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery i2C PSU1 i2C PSU1 i2C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Sofe Mode Auto Safe Mode Auto Safe Mode Auto Safe Mode Temp (C) Voltage (V) Rotation (dps)	RT MIN 55.5 35.5 0.0 0.0 FAIL OK OK 0.0 1 Count: 27 wd 0 ec 1 mr 0 n dac 156 i2c 28 s FALSE TRUE RT MIN 4.2 -30.2 1.2 0.0 0.9 -0.8	MAX 58.2 -0.0 -B c4 -S spi 0 m -G MAX 39.3 5.6 Vc 5.8 Vc 5.8 Vc 1.4 R	Uptime: 144 attery ill A + B + C (V) Y Panel mp (C) itage (V) itation (dps)	RT MIN 3.94 3.73 RT MIN 6.2 -25.2 1.4 0.0 -0.1 -0.7	Min: MAX 4.45 MAX 38.8 4.9 1.4	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) -+Z Panel Temp (C) Voltage (V) Rotation (dps)	RT 6.1 32.5 RT 5.3 3.9 0.9	 Deco 65915 65915 5.6 16.4 16.4 MIN -26.6 0.0 0.1 	MAX 980.2 34.9 MAX 57.3 4.6 1.8
- Radio RX Ter RSSI (TX Ant RX Ant - Experi	AO-85(F al Realtin mperature (C) dBm) enna tenna riments	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed Deployed RT MIN OK	ANSPO 608 Upt 33.3 -65.0 MAX	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpm Battery 12C PSUI 12C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Soft Error Safe Mode Auto Safe Mode Auto Safe Mode Auto Safe Mode Temp (C) Voltage (V) Rotation (dps)	RT MIN 55.5 35.5 n) 0.0 0.0 FALL K 0K OK 0.0 1 Count: 27 wd 0 ec 1 mr 0 n dac 156 126.28 s FALSE FALSE FALSE TRUE RT MIN 4.2 -30.2 1.2 -0.0 0.9 -0.8 -Y Panel -Y Panel -Y Panel	MAX 58.2 -0.0 -0.0 -0.0 -0.0 nf 0 tn -0.0 -0.0 MAX -0.0 -0.0	Uptime: 144 attery ill A + B + C (V) Y Panel mp (C) Itage (V) tation (dps)	RT MIN 3.94 3.73 RT MIN 6.2 -25.2 1.4 0.0 -0.1 -0.7 -ZPanel	Min: MAX 4.45 MAX 38.8 4.9 1.4	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) -+2 Panel Temp (C) Voltage (V) Rotation (dps)	RT 6.1 32.5 RT 5.3 3.9 0.9	65915 65915 5.6 16.4 MIN -26.6 0.0 0.1	ded: 31 MAX 980.2 34.9 MAX 57.3 4.6 1.6
- Radio RX Ter RSSI (TX Ant RX Ant Vander	AO-85(F al Realtin mperature (C) dBm) enna tenna riments	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -1114 -135.5 Deployed Deployed Deployed RT MIN OK	MANSPO 508 Upt 33.3 -55.0 MAX	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery 12C PSU1 12C PSU2 12C Ground Resets Diagnostic Info Hard Error Safe Mode Auto Safe Mode Auto Safe Mode Auto Safe Mode Auto Safe Mode Auto Safe Allowed FX Panel Temp (C) Voltage (V) Rotation (dps) RT MIN MAX 2.4 - 29 - 39.8	Max: F RT MIN 55.5 35.5 0.0 0.0 FAIL OK 1 Count: 27 wd 0 ect 1 mr 0 n dec 156 i2c 28 s FALSE FALSE FALSE TRUE RT MIN 4.2 -30.2 1.2 0.0 0.9 -0.8	MAX 608 58.2 -0.0 -0.0 B spi 0 m Ce spi 0 m Te 5.6 1.4 RT 3.6 1.4 Te	Uptime: 144 attery II A + B + C (V) Y Panel mp (C) Itage (V) tation (dps) MIN MAX -28.8 37.9	RT MIN 3.94 3.73 RT MIN 0.01 -0.7 -Z Panel -Z Temp (C) -Venne(C)	Min: MAX 4.45 MAX 38.8 4.9 1.4	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) +Z Panel Temp (C) Voltage (V) Rotation (dps) RT< MIN	RT 6.1 32.5 RT 5.3 9.9	 Deco 65915 MIN 5.6 16.4 MIN -26.6 0.0 0.1 	MAX 980.2 34.9 MAX 57.3 4.6 1.6
- Radio RX Ter RSI (TX Ant RX Ant - Experi Vander	AO-85(F al Realtin mperature (C) dBm) enna tenna riments	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -1114 -135 Deployed Deployed RT MIN OK -X Panel Temp (C) Voltage (V)	ANSPO 008 Upi MAX 33.3 -65.0 MAX MAX	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery i2C PSU1 i2C PSU2 i2C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Soft Error Safe Mode Auto Safe Mod	Max: F RT MIN 55.5 35.5 0.0 0.0 FAIL OK OK 0.0 dec 156 22.2 FALSE FALSE TRUE RT MIN 4.2 .9.0 .9.8 -Y Panel Temp (C) Voltage (V) Voltage (V)	MAX 58.2 -0.0 Bando In appi 0 m MAX 39.3 5.6 1.4 Ter 3.6 1.6	Uptime: 146 attery II A + B + C (V) Y Panel mp (C) Itage (V) itation (dps) MIN MAX -28.8 37.9 0.0 5.5	RT MIN 3.94 3.73 RT MIN 6.2 -25.2 1.4 0.0 -0.1 -0.7 Z Panel Temp(C) Voltage (V) Voltage (V)	Min: MAX 4.45 MAX 38.8 4.9 1.4	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) -+2 Panel Temp (C) Voltage (V) Rotation (dps) RT< MIN	RT 6.1 32.5 RT 5.3 3.9 0.9	MIN 5.6 16.4 MIN -26.6 0.0 0.1	ded: 31 980.2 34.9 MAX 57.3 4.6 1.6
Radic RATer RSI (J X Ant Exper Vander	AO-85(F al Realtin mperature (C) dBm) enna enna riments riments	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -1114 - 135.5 Deployed Deployed RT MIN OK RT MIN OK -X Panel Temp (C) Voltage (V) E TYPE (466067)	ANSPO 08 Upt MAX -55.0 MAX BAT	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery i2C PSU1 i2C PSU1 i2C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Soft Error Soft Error Safe Mode Auto Safe Safe Mode Auto Safe Safe Mode Auto Sa	RT MIN 55.5 35.5 0.0 0.0 FAIL OK 0K 0 1 Count: 27 wd 0 ec 1 mr 0 n dec 156 i2c 28 s FALSE FALSE TRUE RT NIN 4.2 0.9 -0.8 -Y Panel Temp (C) Votage (V) 8ATT_C_V 0 2807	Resets: 608 MAX 58.2 -0.0 B C4 S8.2 -0.0 C4 C4 S8.2 C4 C4 C4 C4 C4 C4 C4 C4 C4 C4	Uptime: 146 attery attery	RT MIN 3.94 3.73 RT MIN 6.2 -25.2 1.4 0.0 -0.1 -0.7 Temp(C) Voltage(V) Voltage(V)	Min: MAX 4.45 MAX 38.8 4.9 1.4	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) -+2 Panel Temp (C) Votage (V) Rotation (dps) RT NIN A2.8 -30.6 1.4 0.0 BATTBoard PANE	RT 6.1 32.5 RT 5.3 3.9 0.9	NIN 5.6 16.4 MIN -26.6 0.0 0.1	ded: 31 980.2 34.9 MAX 57.3 4.6 1.6
Reset	AO-85(F al Realtin mperature (C) dBm) enna enna friments fibilt Radiation 608 1 608 1 608 1	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed Deployed RT MIN OK RT MIN OK C Femp (C) Voltage (V) E E 466037	ANSPO 308 Upt MAX 3.3 -65.0 MAX BAT 1 1	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rp) Battery 12C PSU1 12C PSU1 12C PSU2 12C Ground Resets Diagnostic Info Hard Error Soft E	RT MIN 55.5 35.5 0.0 0.0 FALL Count: 27 wd 0 ec 1 mr 0 n dec 156 i2c 28 s FALSE FALSE TRUE NIN 4.2 -30.2 1.2 0.0 0.9 -0.8 Temp (C) Voltage (V) BATT_C_V 0 0 2807 0 2811	Resets: 608 MAX 58.2 -0.0 and 0 m Batting RT RT RT RT Ca A Ca Ca A Ca Ca Ca Ca Ca Ca Ca Ca Ca Ca	Uptime: 144 attery all A + B + C (V) Y Panel mp (C) itage (V) tation (dps) MIN MAX -2.8.8 37.9 0.0 5.5 BATT_B_T 0 0 0	RT MIN 3.94 3.73 RT MIN 6.2 -25.2 1.4 0.0 -0.1 -0.7 Temp (C) Voltage (V) BATT_C_T T 0 0 0 0	Min: MAX 4.45 MAX 38.8 4.9 1.4 OTAL_BAT C	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) -+2 Panel Temp (C) Voltage (V) Rotation (dps) RT MIN MAX 2.8 -30.6 43.6 1.4 0.0 5.5 BATTBoard PANE 0 0 0	yloads ime: 14 RT 6.1 32.5 RT 5.3 3.9 0.9	MIN 5.6 16.4 MIN -26.6 0.0 0.1	MAX 31 MAX 980.2 34.9 34.9 MAX 4.6 1.6 1.6
RST (In the second seco	AO-85(F al Realtin mperature (C) dBm) enna tenna triments tribilt Radiation volta Radiation 1 606 1 60	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed RT MIN OK RT MIN OK C C Temp (C) Voltage (V) E TYPE 466003 466003 466009 466099	ANSPO 308 Upt MAX 33.3 -65.0 MAX MAX 1 1 1 1 1	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpm Battery 12C PSUI 12C Ground Resets Diagnostic Info Hard Error Soft Error Soft Error Safe Mode Auto Safe Mode Aut	RT MIN 55.5 35.5 0.0 0.0 FALL 0K OK 0 Count: 27 wd 0 ec 1 mr 0 n dec 156 i2c 28 s FALSE FALSE TRUE 7 RT MIN 4.2 -30.2 1.2 0.0 0.9 -0.8 -Y Panel Temp (C) Voltage (V) 2807 0 2809 0 2811 0 2811 0 2811 0 2817	MAX 608 MAX 58.2 -0.0 B nf0 tn B spi0 n T MAX X S5.6 1.4 RT 3.6 1.6 1.6 BATT_A_T C C C	Uptime: 144 attery all A + B + C (V) Y Panel mp (C) itage (V) tation (dps) MIN MAX -28.8 37.9 0.0 5.5	RT MIN 3.84 3.73 RT MIN 3.84 3.73 RT MIN 62 -52 1.4 0.0 0.1 -0.7 Temp (C) Voltage (V) BATT_C_T T 0 0 0 0 0 0	Min: MAX 4.45 MAX 38.8 4.9 1.4 OTAL_BAT 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) -+Z Panel Temp (C) Voltage (V) Rotation (dps) RT MAX 2.8 -30.6 1.4 0.0 0 0 0 0 0 0	yloads ime: 14 RT 6.1 32.5 8 8 8 8 9 0.9 0.9	MIN 5.6 16.4 MIN -26.6 0.0 0.1	ded: 31
Radic RX Ter RSSI (i RX Ant Expension Vander	AO-85(F al Realtin mperature (C) dBm) enna tenna riments riments ribilt Radiation foos 1 608 1 608 1 608 1 608 1 608	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -1114 -135.5 Deployed Deployed RT MIN OK RT MIN OK -X Panel Temp (C) Voltage (V) E TYPE 466067 7 466038 466094 465994 465994	ANSPO 308 Upt MAX 333 -65.0 MAX BAT 1 1 1 1 1	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery 12C PSU1 12C PSU2 12C Ground Resets Diagnostic Info Hard Error Safe Mode Auto Safe Mode A	RT MIN 55.5 35.5 0.0 0.0 FAIL OK 0K 0 1 Count: 27 wd 0 ect hm 0 n dac 156 i2c 28 s FALSE FALSE FALSE TRUE RT MIN 4.2 -30.2 1.2 0.0 0.9 -0.8 -Y Panel Temp (C) Valtage (V) 2807 0 2811 0 2817 0 2821	Resets: 608 MAX 58.2 -0.0 api 0 m BATT_A_T C C C C C C C C C C C C C	Uptime: 144 attery ill A + B + C (V) Y Panel mp (C) itage (V) itation (dps) MIN MAX -28.8 37.9 0.0 5.5 BATT_B_T 0 0 0 0 0 0 0	RT MIN 3.94 3.73 RT MIN 3.94 3.73 RT MIN -01 -0.7 -22 Panel -22 1.4 0.0 -0.1 -0.7 Voltage (V) Voltage (V) BATT_C_T T 0 0 0 0 0 0 0 0 0 0	Min: MAX 4.45 MAX 4.45 DTAL_BAT 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Telemetry Pa Resets: 608 Upt PSU Current (mA) Board Temp (C) +Z Panel Temp (C) Voltage (V) Rotation (dps) RT MIN MAX 2.8 -30.6 43.6 1.4 0.0 5.5 BATTBoard 0 0 0 0 0 0 0 0 0 0 0	yloads ime: 14 RT 6.1 32.5 8 8 8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	NIN -26.6 0.0 0.1	ded: 31
Radic RATer RSSI (4 TX Antr RSSI (4 Vander Vander	AO-85(F al Realtin mperature (C) dBm) enna tenna fiments fibilt Radiation fold fold 1 fold	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed RT MIN OK RT MIN OK -X Panel Temp (C) Voltage (V) E TYPE 466052 465036 4659590 4659595 465955	MAX 333 350 MAX BAT 1 1 1 1 1 1	NDER Ime: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery 12pin (rpn Safe Mode Auto S	Max: F RT MIN 55.5 35.5 0.0 0.0 FAIL OK OK OK 1 Count: 27 wd 0 ec 1 mr 0 n dac 156 i2c 28 e FALSE FALSE TRUE RT MIN 4.2 .30.2 1.2 0.9 -0.8 -Y Panel Temp (C) Voltage (V) 2809 0 2809 0 2811 0 2821 0 2821 0 2821 0 2821 0 2821	Resets: 608 MAX 58.2 -0.0	Uptime: 146 attery II A + B + C (V) / Panel mp (C) Itage (V) itation (dps) MIN MAX -28.8 37.9 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RT MIN 3.94 3.73 RT MIN 3.94 3.73 RT MIN -25.2 1.4 0.0 -0.1 -2 Panel Temp(C) Voltage (V) Voltage (V) BATT_C_T T 0 0 0 0 0 0 0 0 0 0 0 0	Min: MAX 4.45 MAX 38.8 4.9 1.4	Telemetry Pa Resets: 608 Upt - PSU Current (mA) Board Temp (C) Solard Temp (C) +2 Panel Temp (C) Temp (C) Voltage (V) Rotation (dps) Solard 43.6 1.4 0.0 5.5 BATTBoard PANE 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	yloads ime: 14 RT 6.1 32.5 0.9 0.9	MIN 5.6 16.4 MIN -26.6 0.0 0.1	MAX 980.2 34.9 9 MAX 6 1.6 883 883 883 883 883 883 883 883 883 883 883 883 883 883 883 881 881 881 881
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Radio RX Ter RSSI (d) RX Antr CExpete Vander	UPTIM 608 1608 1608 1608 1608 1608 1608 1608	M) Mode: TRJ ne: Resets: 6 RT MIN) 31.7 14.0 -111.4 -135.5 Deployed Deployed RT MIN OK RT MIN OK RT MIN OK RT MIN CK RT MIN CK CK RT MIN CK RT MIN CK CK CK CK CK CK CK CK CK CK	MAXSPO 308 Upt MAX -65.0 MAX MAX BAT 1 1 1 1 1 1 1 1 1 1 1 1 1	NDER time: 1465965 Computer Temperature (C) Spacecraft Spin (rpn Battery 12C Ground Resets Diagnostic Info Hard Error Safe Mode Auto Safe Mode Temp (C) Voltage (V) Rt MIN Auto 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RT MIN 55.5 35.5 0.0 0.0 FAIL OK OK 0 1 Count: 27 wd 0 ec 1 mr 0 n dac 156 i2c 28 s FALSE TRUE RT MIN 4.2 -30.2 1.2 0.0 0.9 -0.8 -Y Panel Temp (C) Voltage (V) 2807 0 2807 0 2811 0 2824 0 2825 0 2835 0 2835 0 2835	MAX 58.2 -0.0 -B -0.0 -0.0 spil 0 m -0.0 -0.0 MAX 39.3 5.6 1.4 T -0.0 R1 -0.0 -0.0 BATT_A_T -0.0 -0.0 0.0 0.0 0.0 0.0 0.0 0.0	Uptime: 144 attery III A + B + C (V) Y Panel mp (C) Itage (V) tation (dps) MIN MAX -28.8 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RT MIN 3.94 3.73 RT MIN 6.2 -25.2 1.4 0.0 0.1 0.7 Temp (C) Voltage (V) Voltage (V) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Min: MAX 4.45 MAX 38.8 4.9 1.4 OTAL_BAT 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Telemetry Pa Resets: 608 Upt Current (mA) Board Temp (C) +2 Panel Temp (C) Voltage (V) Rotation (dps) RT MMAX 28 -30.6 43.6 1.4 0.0 5.5 BATTBoard PANE 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RT 6.1 32.5 RT 5.3 3.9 0.9 0.9 0.9 0.9 0.9 0.9 0.9 0.9 0.9 0	NIN 5.6 15.4 MIN -26.8 0.0 0.1 PANEL PANEL 0.0 0.1	MAX 980.2 34.9 34.9 MAX 57.3 4.6 1.6 1.6 31 883 883 883 883 881 881 881 881 880 881 881 881 880 879 > >
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When the Historical records are hidden because the "Current" radio button is checked, FoxTelem shows the latest real time data from the spacecraft. This is probably what you want if you are listening live to a satellite pass.

If the Historical records are shown then the number of samples to the right of the "Last" button determines how many realtime payloads are shown in the table. This is the latest records.

If you press the "Last" button it changes to "Next" and shows "from Reset" and "from Uptime". Setting the reset and uptime allows you to show a subset of the payloads. This will show a set of payloads forward from that reset/uptime. If you are decoding live then payloads are still stored and can be reviewed later.

If you press the "Next" button it changes to "Range" and allows you to plot a range of Reset and Uptime.

Most people can't think in a Reset/Uptime timebase. Clicking the Display UTC Time at the bottom of the screen will change the search ranges to UTC times. You can use the following formats to enter dates:

YYYYMMDD HHMMSS	- for example 20180101 23:00:00 is 11pm on New Year's Day
YYYY/MM/DD HH:MM:SS	- 2018/01/01 23:00:00 is the same date
dd MMM yy HH:mm:ss	- 01 Jan 18 23:00:00 is the same date again

In addition to entering dates you can enter the words: now, yesterday and launch. Those dates will be automatically inserted.

If you forget the formats you can hover your mouse over the entry boxes, it will show the formats that it allows.

8.2 Graphing Telemetry Values

A graph opens when a telemetry row in the health tab is clicked with the mouse. By default, the graph shows the last 180 readings. A real time value is downloaded once every 10 seconds or so in Data Under Voice (DUV) telemetry mode. So, 180 readings is about 1800 seconds of data, or 30 minutes. This will therefore show a complete pass of the satellite without changing the settings.

The graph below shows the Internal Temperature of the onboard computer or Internal Housekeeping Unit (IHU). The time axis is recorded on the spacecraft and shows Uptime in seconds since the last reset, with the reset number underneath the first Uptime label.





You can plot more or fewer samples by changing the number from 180 and hitting enter.

When the "Last" button is shown, FoxTelem plots a continuously updating graph for real time monitoring of the spacecraft. This is probably what you want if you are listening live to a satellite pass.

If you press the "Last" button it changes to "Next" and shows "from Reset" and "from Uptime". Setting these you can plot a subset of the data. This will no longer automatically grab the latest samples from the spacecraft, but rather will plot samples forward from that reset/uptime. If that includes the latest samples, then you will still see them appear live. If it does not, then the data will remain static. If you are completely confused and the graph is not doing what you want, then hit the reset button in the top right to reset the graph to its default values.

If you press the "Next" button it changes to "Range" and allows you to plot a range of Reset and Uptime.

Most people can't think in a Reset/Uptime timebase. Clicking the UTC button at the top of the graph will change the search ranges to UTC times. You can use the following formats to enter dates:

YYYYMMDD HHMMSS	- for example 20180101 23:00:00 is 11pm on new years day
YYYY/MM/DD HH:MM:SS	- 2018/01/01 23:00:00 is the same date
dd MMM yy HH:mm:ss	- 01 Jan 18 23:00:00 is the same date again

In addition to entering dates you can enter the words: now, yesterday and launch. Those dates will be automatically inserted.



If you forget the formats you can hover your mouse over the entry boxes, it will show the formats that it allows.

Continuous Plot

If no data is received from the spacecraft for some time, then you probably do not want to plot big empty spaces. In that case, the graph automatically cuts out blank sections of the data. This allows you to see several passes one after the other, without large gaps in between them. If you want to show the data in the right positions on the graphs timeline then tick "Continuous".

Plotting data with gaps in it using a timebase that continually resets makes plotting labels at the bottom of the graph a bit tricky. By default FoxTelem plots labels spaced evenly, but they are not round values. If you click the Round Labels checkbox then FoxTelem will do its best to create labels that are rounded to sensible values. This may result in gaps. Clicking "Continuous" may solve that, but it may not be what you wanted.

Copy / Paste

There are three ways to copy data from the graph.

Firstly, your Operating System probably has a print screen function. In Windows Alt-PrntScrn will copy just the active window and will allow you to past the result into another document.

If you want to have just the graph itself, then use the Copy button in the top right. The previous graph is show below, copied in this way.



Finally, you can save the data values to a csv file using the save button. This will save the data that you have selected for display.

Average and First Difference



In addition to the reset, copy and save buttons, there are two buttons in the top right that draw an additional graph trace.

AVG draws a running average by summing the samples around a given point. The default is 12 samples, but you can change the amount in a new field that appears on the bottom of the graph. Here is a 1200 average plot of the rotation around Z for AO-85, showing a month of data (or about 21000 samples). Large averages take a while to plot, so you may have to wait as it redraws.



The dx (or delta x) button plots the first difference of the samples (which is equivalent to the first derivative for a continuous graph). Try that with a frequency plot of the last pass and see if you can tell how TCA is calculated.

Show Sun

If FoxTelem has valid Two Line Elements (TLEs) then we can add a background color to show when the spacecraft was in sun or in eclipse. The plot below shows the battery voltage for AO-91 for the last day.





8.3 Multiple Variables on one graph

The "+" sign on the top left of a graph can be used to add additional traces. If we add BATT_C_V, the Battery Voltage, to the IHU Temperature graph then we get the following graph. Note that the Voltage is now shown with a new axis on the right. You can keep adding additional traces as long as the units are the same as one of the two vertical axis. All other graph functions work as expected, including exporting data to a file, which exports all variables chosen.



8.4 Earth Plots

From Version 1.06 most parameters can be plotted against the surface of the Earth. To open an Earth Plot, Right Click or Control-Click the telemetry row. The chart below is an Equirectangular Projection

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of AO-91s battery voltage for about 10 days. It clearly shows where the stations are that collect telemetry. If you plot this for you own data, you get a nice cloud around your ground station showing your reception horizon.



Earth plots are only possible if you have historical Two Line Elements (TLEs) for the dates that you are plotting. If you just have the latest TLE then data plotted more than a month in the past is very inaccurate. FoxTelem builds a set of historical TLEs for you automatically, but it only started when you installed FoxTelem v1.05. You can replace the TLE file with a full history by grabbing a TLE history file from AMSAT. They can be found here for some spacecraft: http://www.amsat.org/tle/historical/

8.5 Radiation Experiment

The Vanderbilt University Radiation Experiment is testing Commercial Off the Shelf (COTS) memory chips in space to see how they are affected by radiation.

8.6 Camera Images

Camera Images are downloaded in High Speed telemetry mode if the Virginia Tech Camera is present on the spacecraft. Fox-1A (AO-85) and RadFxSat / Fox-1B (AO-91) do not have a Camera, but Fox-1Cliff (AO-95) and Fox-1D (AO-92) spacecraft do. However, AO-95 is not functioning correctly, likely due to a receiver issue, and the spacecraft cannot be commanded to take pictures. AO-92 is now sadly dormant, but you can see the archive of pictures taken here: https://www.amsat.org/tlm/showImages.php?id=4



9 Making Measurements

9.1 Overview

In addition to the telemetry and science data received from the satellite, you can make measurements at your ground station and store them for analysis. Out of the box, FoxTelem can measure:

- Signal To Noise level of the received bits
- Signal To Noise level of the RF (in IQ mode)
- RF signal strength (in IQ mode)
- Azimuth and Elevation (from SatPC32, using the DDE interface on Windows)
- Frequency (in IQ mode or using the SatPC32 DDE interface on Windows)
- Time of Closest Approach (TCA) through Doppler analysis (in IQ mode)

Each of these measurements are stored at the time a frame is detected and they are timestamped with both the current UTC time and with the reset/uptime that was on the received frame. This gives a sample about every 5 seconds.

9.2 Signal to Noise Measurements

Signal to noise measurements can be used to optimize your station and to help understand how radio signals are propagated from the spacecraft. Store the results and compare them when you have made changes. What difference does a pre-amp make? A higher gain antenna? A different receiver? What is the difference in signal to noise vs elevation at your QTH (ground station location)? Does the RF signal to noise ratio correlate with the bit signal to noise ratio? Which should be optimized?

9.3 Azimuth and Elevation

FoxTelem cannot read your rotator directly, but it can calculate the expected position or grab the information from another program such as SatPC32 using its DDE interface.

If you would like FoxTelem to calculate this information, then select "FoxTelem Calculates Position" from File > Settings. If the option is greyed out, then you need to first provide the position of your ground station.

On Windows you can choose "Read Position from SatPC32" on the File > Settings window. See the DDE Interface section of SatPC32's manual for details on setting this up.

9.4 Time of Closest Approach

The Doppler on the frequency of the satellite tells us something about how the spacecraft is moving relative to our current position on the earth. We can use this to work out when the spacecraft is closest to our ground station. This is the Time of Closest Approach (TCA) and it is a very helpful measurement to confirm or refine orbital elements. We can also use it to see how stable the downlink frequency is. TCA is especially useful when a spacecraft has recently been launched.

You can measure TCA by logging the frequency of the downlink signal. If the frequency at the satellite was unconditionally stable and we knew exactly what frequency it was on, then you could measure when the received frequency at your ground station equals the nominal frequency and call it



TCA. However, a small 10cm CubeSat has a challenging thermal environment and we cannot rely on the frequency of the downlink for this measurement. Instead, this measurement will tell us what the nominal frequency is.

If you are running FoxTelem in IQ mode then it will store the downlink frequency throughout a pass. At the end of a pass it calculates when the frequency changes at the fastest rate. This should be at or very near to the nominal downlink frequency. It then stores the time when this happened (TCA) and the frequency at that time. You can see the measurements for the last pass on the measurements tab.

We cannot measure TCA by reading the frequency from SatPC32 or another prediction program. We need to know the actual frequency of the satellite, not the calculated frequency.

9.5 Sky Plots of Measurements

There are two options for graphing measurements. You can click on the measurement value and open a graph, just as you can for spacecraft telemetry. In addition, there is a button to the right of each value that opens a sky plot, which plots the data against elevation and azimuth, as seen from your ground station. Below you can see the received signal strength in dBm plotted against the satellites position in the sky. A darker color is a stronger signal.



10 Getting Better Decodes

10.1 Frequency and Tracking

The provided values for Frequency are nominal. These are shown in the Frequency and Tracking section of the Spacecraft parameters window, which you can access by clicking on a spacecraft name on the Spacecraft menu. When we say nominal, we mean that the spacecraft was setup in the lab on earth to have a frequency that matches the value we publish. Once in space the frequency can be slightly different, mostly due to thermal effects.



For example, careful measurements at WA4SCA's ground station show that all the Fox spacecraft center 1Khz higher, and HO-107 was 3.5KHz higher. After the TLEs settle down, he runs FoxTelem in full screen, and adjusts the center value so that it properly tracks the actual values, once Doppler correction is layered on top.

10.2 Eye Diagram

A subtle distortion in the FSK eye diagram like the plot on the left perhaps shows a mismatch between the sample rates at some point in the chain. A much better eye diagram is shown on the right.



First of all, set the sample rate to 48000 samples per second if possible. The divides evenly into 200 bps and 9600 bps and gives slightly better decodes. With a strong signal it makes no difference, but if the signal is distorted or weak then it can help.

Secondly, make sure that the sound card or audio source is also set to 48000. Windows likes to set everything to 44100 by default, so you need to go into the Control Panel to change it. If you are using a virtual cable to connect an SDR to FoxTelem, then be aware that when initially started cables will be defaulted to 44100 by Windows. FoxTelem or the SDR can not then reset them to 48000. Virtual Audio Cable is a good example of this and it mentions the issue in its manual. When you configure a new cable you give it a range of sample rates. Windows will then pick 44100 if it is available. Even if that is not what you wanted. So I setup two cables, and narrowed the range of samples rates to one value. One cable is then for 48000 and the other is for 192000. Then there is no question about the rate that Windows will give them.

The eye diagram is shown below decoding a DUV signal. The more open the eye is the better the signal will decode. If there is less noise then the bits that make up the eye fit more precisely on top of each other and the blue lines are thinner. The signal to noise ration of the eye is measured from the average high value to the average low value. The red bars are therefore in the middle of the set of blue lines. For DUV an Eye SNR of 2dB or more is needed to decode. 6.7dB is excellent. More is even better.





10.3 PSK

You can display an eye diagram and/or a phasor for PSK. The Eye diagram functions as described above. The phasor is described in the section below.

When you decode PSK audio you have two traces. The black trace is the actual audio. Notice that this is still clearly a PSK signal together with the expected phase shifts even though it is now down converted to around 1.2kHz. The blue trace then shows the recovered bits. For a Costas Loop the recovered bits look like the bits that were originally encoded. We recover their exact shape because the frequency and phase are locked to the data carrier.



The Dot Product decoder also displays the audio in black. There are 100 bits decoded at a time, rather than 40, but otherwise this looks the same as the Costas Loop. The blue trace is no longer the original bit shape. It is the energy of the bits. We can plot the recovered bit shape and it looks very similar to the Costas Loop, but it is continuously oscillating because we are not locked in phase. It does not help us determine if we have the signal tuned correctly. The decoder uses the energy of each bit to determine its value and this is more helpful to plot. Note that the SNR of the eye diagram appears much less and this is reflected in its ability to decode noise signals.





10.4 PSK Phasor

For BPSK you can display an eye diagram and/or a phasor. The phasor plots the phase of each sample. The phasor is shown below for a Costas Loop. The red notation has been added to aid explanation. FoxTelem does not plot it.

If we have a point plotted on the red dotted "unit circle" then it has a Magnitude of 1 and a phase given by the angle from 0. The angles for 0 and 180 are shown. The blue dots and noise are from the Costas loop. The loop locks the signal so that the transitions are between 0 and 180 degrees. This is what we expect to see.



The phasor from the Dot Product BPSK decoder is shown below. Now the phasor is a straight line rather than two dots. This tells us that our samples are varying in magnitude as well as phase. We also have a phase variation between 30 degrees and 210 degrees rather than between 0 and 180. The Dot Product decoder is a "non Coherent" decoder. It does not need to lock the phase to exactly 0 and 180 degrees. The phase will rotate, sometimes quite fast, and we still decode the bits.





10.5 High Speed Bandwidth

High speed data from Fox is 9600 bits per second FSK. The FM signal is 20kHz wide. Make sure that the radio you are using is on a wide enough setting to accommodate.

11 Settings

The settings screen is accessed from the File menu. This contains 6 types of options:

- Files and Directories
- Decoder Options
- Server Upload Parameters
- Formatting
- Measurements
- Debug Options



×

Settings

Files and Dir	ectories							
Home directory	C:\Users\chris\.FoxTelem							
Server Data URL	https://www.amsat.org/tlm							
Log files directory	C:\Users\chris\Deskto	p\Test\MAN_TEST		Browse				
Ground Stati	ion Params		Decoder Options					
Groundstation Nam	ie	GOKLA	Upload to Server					
Primary Server		tlm.amsat.org	Use Left Stereo Channel					
Secondary Server		tlm.amsat.us	Swap IQ					
	Locator from Lat Lo	ng: IO91tp	PSK: Use 12 kHz IF					
Lat (S is -ve)		51.64583	Debug Options					
Long (W is -ve)		-0.375	Debug Frames Debug Fields					
Altitude (m)		0	Debug Camera Frames Debug Bits					
RF-Receiver Descri	iption	NONE	Debug Bytes Debug Values					
Formatting			Use RS FEC					
Health Module Fon	t Size	12	Use RS Erasures					
Graph Font Size		12	Debug RS					
Measureme	nts □ Log Fre □ Read p ☑ FoxTele ☑ FoxTele ☑ Auto S	eq from SatPC32 in AF mode osition from SatPC32 em Calculates Position em Calculates Doppler tart Decoder when above horizon	Debug audio levels Debug Find Signal Debug (Calc) Doppler Continually Use Native File Chooser DUV Frame Length: 960 bits HS Frame Length: 52720 bits					
		Save	Cancel					

11.1 Files and Directories

The Home Directory is noted because this is the location of the properties file. It is unlikely that you will need to directly edit the properties, but it is good to know where they are stored.

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The Server Data URL is the location of the server data. If you go to this URL you will be able to see the data that has been uploaded by ground stations around the world. This is also the URL used by FoxTelem to download data from the server.

The Log files directory sets the directory that the downloaded telemetry data is stored in. FoxTelem has a number of files that it stores on disk. It's worth describing them first. They are as follows:

- spacecraft directory that stores the spacecraft configuration files
- images directory that stores images downloaded from the Virginia Tech Camera (if present)
- seq.dat file that stores the next sequence number to be sent to the server
- rawHSframes.log queue of the high-speed frames to upload to the server
- rawDUVframes.log queue of the low speed frames to upload to the server
- FoxTelemDecoder.log the log file from FoxTelem. Updated if the Setting "Enable Logging" is checked.
- FoxTelem.jar The FoxTelem core program classes
- FoxTelem.properties The FoxTelem settings that are stored between program executions. Editable from the File>Settings screen and elsewhere in the program. Not designed to be user editable. This is stored in the Home Directory, shown at the top of the settings screen
- Fox3jpg_index.dat An index file the stores the images that have been downloaded from the VT Camera. Present on Fox-1C
- FOXDB Your logs of the payloads downloaded from Fox. Additional log files will be created for other satellites. You do not need to send this data to AMSAT. This is your own personal archive for experimentation and analysis. You can send it to other people, who can open it with FoxTelem by pointing FoxTelem at a different directory where they save the files.

11.2 Decoder Options

Upload to Server – select this if you want to send your collected data to the AMSAT telemetry server. You will need to supply some of the Ground Station parameters if you check this option, specifically a Ground Station Name and your location.

Find Signal – Check this to automatically follow the signal if you are decoding from FoxTelem's SDR. Checking this unchecks "FoxTelem calculates Doppler"

Store FCD Params – Check this if you want the FCD parameters to be saved when you exit. This is useful if you want to recover the parameters of your ground station restarts after a power failure. Note that it can conflict with other programs running on the same computer.

Use Left Stereo Channel – The default is for FoxTelem to read audio from the left stereo channel of your soundcard. If you uncheck this, it will read from the right. There is no issue if you supply audio to both channels. This setting is ignored in IQ mode, when both channels are read.

Swap IQ – This swaps the I and Q channels in the IQ decoder



PSK: Use Costas – This uses the Costas Decoder when we are decoding BPSK, rather than the Dot Product decoder. The Costas Decoder needs less Signal To Noise Ratio for decodes, but is slightly more vulnerable to fading.

11.3 Ground Station Parameters

Ground station name is the unique identifier that you will use to store data on the AMSAT telemetry server. If you are a licensed Amateur Radio Operator, we recommend you use your callsign. Otherwise use the name of your organization or something else that will be unique. This is limited to 32 characters.

To be clear, we do not enforce uniqueness. We only use the name to keep track of how many frames each station supplied.

Primary and Secondary server are not user editable

Latitude / Longitude or Locator need to be specified if you supply decoded data to AMSAT. You can either enter a Maidenhead locator or your lat/long. One will calculate the other

Altitude will be supplied to AMSAT along with your data if you specify it.

RF-Receiver can be specified to give us an idea of the types of stations that are in operation. This is limited to 50 characters.

11.4 Formatting

Health Module Font Size – change the size of the font on the Satellite tabs so that it is more readable or so that it fits in the space available

Graph Font Size – change the size of the font on the graph axis

11.5 Measurements

Log Freq from SatPC32 in AF Mode – this is only visible on the Windows platform. Select this if you want FoxTelem to read the frequency from SatPC32 using DDE when deciding in AF mode. This might be useful if SatPC32 is tuning your radio and you want to store the actual frequency the radio was tuned to each time a frame is received

Read Position from SatPC32 – this is only visible on the Windows platform. Select this if you want FoxTelem to read the satellite position from SatPC32 using DDE. This will allow the Azimuth and Elevation to be stored for later analysis. It will also allow automatic start/stop of the decoder if "Start decoder when above horizon" is also set

FoxTelem calculates position – If this is selected then FoxTelem will calculate the position of the spacecraft. It will automatically download the needed Keplerian Elements from AMSAT.

FoxTelem calculates Doppler – Set this when you want FoxTelem to tune the SDR to the predicted frequency of the spacecraft. This toggles "Find Signal" off.

Auto Start decoder when above horizon – when selected the decoder will be off unless a tracked spacecraft is above the horizon. This limits the amount of processing power that FoxTelem consumes.



For position and Doppler calculation to work, whether from SatPC32 or by FoxTelem, the name of the Spacecraft needs to match the name in the Keplerian elements file. FoxTelem uses the nasabare.txt Two Line Element (TLE) / Keplerian Element file. You can check the names here: https://www.amsat.org/amsat/ftp/keps/current/nasabare.txt If the name is different, then you can change the name in FoxTelem on the spacecraft parameters screen.

If FoxTelem cannot find the needed Keplerian elements, then it will warn you. This is a problem at first launch. If elements have been released, but are not yet in nasabare.txt, then you can manually write them into the spacecraft sub-directory of you logfile directory. The file is named foxX.tle, where X is the Fox-ID and contains one Two Line Element (TLE) set for each set of Keplerian elements downloaded for that spacecraft. They are stored in Epoch order. At launch you just need one TLE set. e.g. for Fox-1A the file is called FOX1.tle and will contain one or more TLE sets like this, with the Epoch shown in bold. If there are multiple TLEs then the Epoch will be different for each:

AO-85 1 40967U 15058D **17278.51421614** .00000880 00000-0 11831-3 0 01124 2 40967 064.7745 244.1947 0178987 037.6014 323.7456 14.75520632016072

11.6 Debug Options

Enable Logging: Write additional debug and errors to the log file. This creates a significant volume of data and should only be used temporarily.

Debug Frames: Print out information about the decoded frames, such as the start and end bit positions, the payload type, the number of erasures and corrections.

Debug Fields: Print out the decoded payloads field by field, so that you can see all of the raw values in the log file.

Debug Bits: Print out a very verbose listing of the bits decoded

Debug Bytes: Print out the decoded payload bytes

Debug Values: Enter a special mode where the audio display is frozen and can be advanced with a play and pause button. Print out the sample number and show the way that the audio is sliced into bits.

Use RS FEC: Run the RS decoder to error correct and check frames. If this is off then uncorrected and corrupt frames will be passed as valid. This can be useful in the early stages of debugging a new format or spacecraft. In most cases it should be left on.

Debug Clock: Prints out details of the clock recovery, showing how much the clock was adjusted each time it was updated.

Debug Missed Audio: Displays some debug information on the audio graph to help understand the performance of the audio sampling sub-system.

Debug Find Signal: Prints out details of the find signal state machine to the log file.

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Debug Calc Doppler Continually: Calculate Doppler and tune the SDR for the first spacecraft in the priority order. Do not wait for the spacecraft to be above the horizon.

Use Native File Chooser: When files are opened from the GUI, the default is to use the File choosing window that is supplied by the Operating System. If you have problems with opening files then try unchecking this. A cross platform Java File Chooser will then be used.



12 Spacecraft Configuration

The spacecraft directory contains a number of files that are used to setup FoxTelem for each Fox Satellite. As more Fox Satellites are launched, we will supply more configuration files.

These files are explained in detail in the AMSAT FoxTelem Designers Handbook. A pdf of this document is supplied with FoxTelem and the latest version is available from <u>www.g0kla.com</u>. This document contains a summary of the information and some of the values used in the early Fox spacecraft.

The directory contains a set of files such as the following, with additional files if more Satellites are configured or more experiments are onboard.

- FOX1x_fm.dat The spacecraft configuration file for the Fox 1x Flight Model. This is stored in a subdirectory of your logfiles directory and contains configuration parameters for the spacecraft.
- FOX1x_fm.MASTER The master copy of the spacecraft configuration file stored in the installation directory
- FOX1x_rttelemetry.csv the layout file for the Real Time Telemetry Payloads and the configuration needed to display them in FoxTelem
- FOX1x_mintelemetry.csv the layout file for minimum values payloads
- FOX1x_maxtelemetry.csv the layout file for maximum values payloads
- FOX1x_rssiFM.tab a lookup table for the Received Signal Strength telemetry raw value. There are several look up tables for each satellite.
- jpeg_header.out Virginia Tech's header file for the JPEG images that will be part of FOX-1C
- jpeg_header_low_res.jog Virginia Tech's header file for the Fox-1D (AO-92) images
- measurements.csv the layout file for the ground station measurements
- passmeasurements.csv the layout file for the ground stations pass measurements
- stpHeader.csv the layout of the STP HEADER table. Used by the server.

12.1.1 Adding and Removing Spacecraft

From the spacecraft menu select "Add" to add a new spacecraft to FoxTelem. You will see a list of the spacecraft MASTER files available. Selected one and click Open. It will be installed by FoxTelem.

To remove a spacecraft select "Remove" from the spacecraft menu. You will see a list of the installed spacecraft files. Select the one you want to remove. This will not delete any of the stored telemetry, but it will no longer be visible on the GUI.

12.1.2 Spacecraft Configuration File



A spacecraft configuration file exists for each Fox satellite that you wish to receive data from. We will supply new files as new Fox satellites are launched. If you edit this file, make a backup of the existing file. You can view these parameters from the Spacecraft menu. Here is the Fox-1B screen:

Spacecraft paramaters					
Identification					
Name (for Keps) AO-85 ID: 1 Priority 1 🗸					
Display Name AO-85					
Fixed Pa	ramaters		Frequency and Tracking		
Model: Flight I	Model		Mode	FSK 200bps (Fox1) 🛛 🗸	
Experiment 1:	: Vanderbilt VUC		Downlink Freq (kHz)	145980.0	
Experiment 2: Experiment 3:	: Vanderbilt LEP : Empty		Lower Freg Bound (kHz)	145970.0	
Experiment 4	: Empty		Upper Freg Bound (kHz)	145990.0	
Time Zer	0				
Epoch	Date		Track this spacecraft		
0	08 Oct 15	16:56:10	Use GPS Time to set TO)	
1	14 Oct 15	15:24:15			
2	26 Oct 15	20:32:24			
4	26 Oct 15	20:32:24	Calibration		
5	26 Oct 15	20:32:24	Battery Current Zero	-1.839	
6	08 Nov 15	17:23:27 ¥	RSSI Lookup Table	FOX1A_rssiFM.tab	
Update T0 from Server Delete T0 File			IHU Temp Lookup Table	FOX1A_ihutempSN7.tab	
			VBatt Lookup Table	FOX1A_ihuVBattSN7.tab	
			Use Bus Voltage as VBa	att	
			MEMS Rest Value X	2087	
			MEMS Rest Value Y	2101	
			MEMS Rest Value Z	2045	
Descripti	ion				
Fox-1/ Penn	A is a 1U Cubes State University	at with a U/v FM voi and Vanderbilt Univ	ce transponder and onboa versity	rd experiments from	
				Save Cancel	

The data is stored in a java "properties" file which consists of key-value pairs. A line either starts with a #, meaning it is a comment, or it has a key followed by an = then the value.



The keys in early Fox spacecraft are shown below, for a more complete discussion see the AMSAT FoxTelem designers handbook:

foxId - this is the id of the satellite, where 1 = 1A, 2 = 1B etc. You can not load two satellite configuration files with the same foxid

catalogNumber - this is the NORAD catalog number for the satellite and is unused currently

name - this is the name that is used to extract Two Line Elements TLEs from the Keplerian Elements file. E.g. AO-85. It must match the name in nasabare.txt. If SatPC32 is used to indicate when the spacecraft is above the horizon, then this name needs to be the same as the name in SatPC32.

displayName - this is the name that is displayed in FoxTelem for this satellite. E.g. Fox-1A or AO-85.

description - this is a helpful description so we know which satellite we are talking about

model - this is the model number where 0 = Engineering Model, 1 = Flight Model and 2 = Flight Spare

IHU SN - this is the serial number of the IHU board

EXPx - this indicates what is in experiment x slot, where x is 1 - 4. The value is then a number, which indicates the following: 0 - Experiment slot is empty 1 - Vanderbilt Vulcan Radiation Experiment 2 - Virginia Tech Camera 3 - IOWA State HERCI Experiment 4+ are currently reserved for future use

telemetryDownlinkFreqkHz - the nominal transmit frequency for the downlink telemetry, e.g. 145980 for Fox-1A. See "Getting Better Decodes", which discusses the importance of this.

 ${\tt minFreqBoundkHz}$ – the lower frequency bound when the "Find Signal" algorithm is searching for this satellite

maxFreqBoundkHz - the upper frequency bound when the "Find Signal" algorithm is
searching for this satellite

BATTERY_CURRENT_ZERO - the calibration point for zero battery current, e.g. -1.839 for Fox-1A

rssiLookUpTableFileName - the lookup table to use for RSSI values

ihuTempLookUpTableFileName - the lookup table to use for the IHU temperature.
Specific to each IHU Serial Number

ihuVBattLookUpTableFileName - the lookup table to use for Battery Voltage

rtLayoutFileName - the layout file for the RT Telemetry

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maxLayoutFileName - the layout file for the MAX Telemetry

minLayoutFileName - the layout file for the MIN Telemetry

 ${\tt radLayoutFileName}$ - the layout file for the Raw Radiation Bytes. This is the format that is saved to disk

rad2LayoutFileName - the layout file for the Radiation Telemetry. This is the format displayed in the Vanderbilt Radiation Tab if "Telemetry" is selected.

measurementsFileName - the layout file for the measurements made locally at your
ground station

passMeasurementsFileName - the layout file for the measurements made for each
satellite pass

useIHUVBatt - set to true if the IHU is used to measure Battery Voltage, rather
than the Battery Board.

MPPT Resistance Error - the extra, unintended resistance in the RTD measurement circuit. This circuit measures the temperature of the solar panels. The error resistance value is used in the calculation of the temperature

MPPT Sensor Off Threshold - The solar panel temperature sensors are off when the panel is not illuminated. This raw value is the minimum required for FoxTelem to display a value. Set it to 0 to see all values of the sensor.

12.1.3 Telemetry Layout Files

The telemetry layout files contain a row for each value in the telemetry. These are read by FoxTelem when it starts and are used to parse the received telemetry once it has been demodulated. The first row of the file contains the number of rows, followed by the column names. The number of rows specified then follows, with a value REQUIRED in each column. The file is comma delimited and is easiest to edit in a spreadsheet program such as Microsoft Excel. Make sure you save it as a csv file again.

The columns are as follows:

TYPE - For information only. RT, MAX, MIN or RAD. Ignored by the program

FIELD - The name of the field. Must be unique. Used by FoxTelem to keep track of the value internally.

BITS - The number of bits in the field. (As a side note Fox sends bits with the most significant bit first, but it is little endian, so we get the least significant byte first. This made the decoder more entertaining to write.)

UNIT - The units that the telemetry value will have after we convert the raw value. This is displayed on screens and graphs.

CONVERSION – The conversion routine to run on the raw value. This is an integer value. See Conversions below to understand what the integers mean.

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MODULE – The name of the module on the "Health" tab that this value should be displayed in. If RT, MAX and MIN are displayed on the same line, then this only needs to be set in the RT layout file.

MODULE_NUM – The number specified determines the order of the modules on the Health tab. The first module should be "1". Modules then follow numerically. Modules starting with "10+" are displayed in the lower half of the screen.

MODULE_LINE – This is the line in the module that the value is displayed on, starting with line 1.

LINE_TYPE - A numeric value, with the following meanings:

0- Display value in the Real Time column only on this line. E.g., Antenna Status has no Max or Min value. Confusingly, we use this to display things like "Soft Error" which is only in the MIN Values Payload. So we specify the module and module line for it, but give it LINE_TYPE 0

- 1 Display value in the MAX column never used
- 2 Display value in the MIN column never used
- 3 Display values in ALL columns used for most values

SHORT_NAME – The name that is displayed on the Health Tab for this telemetry value .

DESCRIPTION – The description that appears when the mouse is hovered over this value.

12.1.4 Conversions

It turns out that taking raw values measured by Analog to Digital Converters (ADCs) on the spacecraft and converting them into real, accurate measurements across multiple satellite, is non-trivial. We have therefore specified several conversion routines. Following Fox-1E no more will be added in the future as Curve Conversions will support all future conversion needs. See the next section.

The list of existing Conversion values are defined here:

https://github.com/ac2cz/FoxTelem/blob/master/src/telemetry/BitArrayLayout.java The Conversion routines are implemented here: https://github.com/ac2cz/FoxTelem/blob/master/src/telemetry/FramePart.java

Integer	Name	Description	Conversion
0	CONVERT_NONE	Use the raw value as is	None
1	CONVERT_INTEGER	Use the raw value as an integer	Round to zero decimal placed
2	CONVERT_V25_SENSOR	Treat the raw value as a reading by the 2.5V ADC	Raw * 2.5/4096
3	CONVERT_V3_SENSOR	Treat the raw value as a reading by the 3V ADC	Raw * 3/4096
4	CONVERT_BATTERY	Convert the raw value into a battery voltage depending on the resistor network used to apply the value to the ADC	Battery A uses the 2.5V ADC, Battery B uses the 2.5V sensor / 0.76, Battery C uses the 2.5V sensor / 0.5
5	CONVERT_SOLAR_PANEL	Convert the raw value from the solar panels	Raw * 3V ADC / 0.428

For Fox-1A we had the following conversions:



Integer	Name	Description	Conversion
6	CONVERT_SOLAR_PANEL_TEMP	Converts the raw value to a temperature in Celsius	Lookup the value in the Solar Panel Temperature Table, held inside FoxTelem
7	CONVERT_TEMP	Converts the raw value to a temperature in Celsius	Lookup the value in the Temperature Table, held inside FoxTelem
8	CONVERT_BATTERY_TEMP	Converts the raw value to a temperature in Celsius	Lookup the value in the Battery Temperature Table, held inside FoxTelem
9	CONVERT_BATTERY_CURRENT	Calculate the positive or negative battery current in mA given the voltage across a sense resistor	((rawValue * 2.5V ADC - 0.05) * Battery Zero Value (in the spacecraft file) + 2) * 1000
10	CONVERT_PA_CURRENT	Calculate the PA current in mA given the voltage across a sense resistor	((rawValue * 3V ADC) / 50 / 0.2) * 1000
11	CONVERT_PSU_CURRENT	Calculate the PSU current in mA given the voltage across a sense resistor	((rawValue * 3V ADC) / 0.003)
12	CONVERT_SPIN	SPIN is 3.8 fraction fixed point.	If raw value $> 2^{11}$ (2048) - 1 then value = value - 2^{12} (4096). This gives a signed value which we then divide by 256 to get a signed double
14	CONVERT_RSSI	Converts the raw value to the Received Signal Strength in dBm	Lookup the value in the RSSI table, which is specified in the Spacecraft configuration file
15	CONVERT_IHU_TEMP	Convert the raw value to the IHU internal temperature in Celsius	Lookup the value in the IHU Temperature table, which is specified in the Spacecraft configuration file
16	CONVERT_ANTENNA	Convert the 2 bits into values for the antenna deployment status	0 = Stowed, $1 =$ Deployed
17	CONVERT_STATUS_BIT	Convert the bit into a status value	0 = OK, 1 = FAIL
18	CONVERT_IHU_DIAGNOSTIC	A set of diagnostic bits that are converted into values for debugging the IHU	
19	CONVERT_HARD_ERROR	Watchdog status and the type of error that last reset the spacecraft	
20	CONVERT_SOFT_ERROR	Other non fatal errors	
21	CONVERT_BOOLEAN	Convert the bit into a Boolean value	0 = FALSE, 1 = TRUE
22	CONVERT_MPPT_CURRENT	Calculate the current from the Maximum Power Point Tracker (if installed) based on the voltage across a sense resistor	(rawValue * 2.5V ADC) / 2.5
23	CONVERT_MPPT_SOLAR_PANEL	Calculate the voltage for each solar panel, as measured by the	rawValue * 2.5V ADC * (6.54/2.42)



Integer	Name	Description	Conversion
		Maximum Power Point Tracker	
24	CONVERT_MPPT_SOLAR_PANEL_TEMP	Calculate the temperature of	Lookup the value in the
		each solar panel, as measured by	MPPT Solar Panel
		the Maximum Power Point	Temperature table
		Tracker	
25	CONVERT_16_SEC_UPTIME	Convert Vulcan uptime to	rawValue * 16
		seconds	

12.1.5 Conversions Curves

Version 1.09 of FoxTelem introduces the concept of Conversions based on curves and these will be used on all future spacecraft. A configuration file is specified in the Spacecraft master configuration file as follows:

useConversionCoeffs=true conversionCurvesFileName=GOLF-T_conversion_curves.csv

That tells FoxTelem that this spacecraft will use the new conversion approach and that the configuration file is called GOLF-T_conversion_curves.csv. In that file we find the following type of information.

	А	В	С	D	Е	F	G	Н
1	CurveName	а	bx	cx^2	dx^3	ex^4	fx^5	Description
2	com1_tx_fwd_pwr	-13.019	36.436	-13.107	1.7685	0	(Forward power. Apply to the voltage value from the IHU lookup table
3	com1_tx_ref_pwr	-34.583	0.1727	0	0	0	(Reflected power. Apply to the voltage value from the IHU lookup table
4	8_bit_temp	-20	0.5	0	0	C	(gtemp RT1Temp and RT2Temp IHU supplies as 7.1 fixed point with offset of 20
5	golf-t_bus_voltage	0	0.0399	0	0	C	(0 -255 means 0-13.61V
6	8_bit_voltage	0	0.03026	0	0	C	(3V Prot 2.5V prot VGA Control and others

In the next release of FoxTelem this will be fully supported.

13 Troubleshooting

Symptom	Solution
Poor decodes or no decodes	1. Are you trying to decode directly from the
	radios headphone jack or speaker output? That
	won't work. See the earlier sections of the
	manual on decoding from a radio.
	2. Is the sample rate different to the sound card?
	Has Windows (or another OS) set the sound card
	up with 44100, even though you told it not to?
	3. Is Virtual Audio Cable (VAC) or another
	similar audio transport running at a different rate?
	4. Do you have the free version of Virtual Audio
	Cable (VAC)? It contains a voice announcement
	that impacts decoding and increases the error rate.
	5. Is your SDR outputting audio at a different
	rate?



	 6. Is your SDR audio filtering set to cutoff important frequencies? 7. Is the volume set to high and the wave form is distorted? 8. What is the Signal to Noise ratio of the eye diagram – assuming you have one? It should be 2+, preferably 6+
Decoder stalls when a frame is received	 Is the bit level debugging on, or some other verbose debugging? Check on the File>Settings screen Has the FoxTelemDecoder.log file grown to a huge size? Are you nearly out of disk space?
I am using HDSDR and I have missing lines in the images I am receiving from the Virginia Tech Camera onboard Fox-1C (or another Fox sat)	We have seen a bug in HDSDR where it skips a few bits and the decode is corrupted. Set the Bandwidth to 96000 in HDSDR and the Sample Rate to 96000 in VAC (if you use it) and in FoxTelem. This should work around the issue. That said, in 1.06 and later there is an algorithm to re-insert bits dropped by the audio software. It is enabled from the settings tab.
FoxTelem does not start when I launch it	 Maybe you have a FUNcube dongle connected to your computer and it has crashed. Try unplugging the dongle and restarting FoxTelem. If you edited the spacecraft files, perhaps something is causing FoxTelem to crash. Try putting the default spacecraft files back in place. See if the file FoxTelemDecoder.log has been created in the installation directory. See if this contains and error messages. Try running FoxTelem from the command line to see if any errors are reported to the console. If a file called foxtelem.properties has been created in the installation directory, you could manually edit it and set logging=true. Then try again and see if error messages are written to the console or to the FoxTelemDecoder.log file. If FoxTelem ran previously, try renaming foxtelem.properties temporarily. FoxTelem will create a new properties file when it starts up.
I try to run the FoxTelem.exe file on Windows and it tells me that it is missing MSVCR100.DLL	This is the Microsoft Visual C library and should already be installed with Windows. An



or a similar error	aggressive Uninstall application may have removed it from your system. See this help article from Microsoft: <u>http://answers.microsoft.com/en-</u> <u>us/windows/forum/windows_other-</u> <u>performance/msvcp100dll-missing/9a687c31-</u> <u>0619-4ee9-b511-020985e29b5f</u>
I'm confused about Java on the Mac. Apple do not seem to support it anymore, what is going on?	Before macOS 10.7 (Lion) you used the Apple supplied version of Java (version 6). You should be able to do this through Software Update in the System Preference. Apple no longer maintains the Java runtime environment, so post 10.7.3 you are advised to install the latest runtime environment, which you can download from java.com. However, this is not compatible with FoxTelem on the Mac (even though it is on all other platforms). So you will need to install the old version of Java. See the issue below.
I try to run FoxTelem on the Mac and it tells me that it is a "legacy" app and I need an old version of Java	To maintain compatibility with older Macs (see the question above) we have made FoxTelem available with Java 6. Follow the instructions and install the legacy version.
I was running FoxTelem on my laptop, tablet, windows phone, windows fridge etc and when I came back it looks like the audio was disconnected. The blue audio graph is blank.	Windows, and probably other platforms, can put the audio system to sleep when the computer sleeps or hibernates. This seems to disconnect the audio system from FoxTelem. When the computer awakens, you need to stop and start the decoder to reconnect it. You can prevent this by stopping the computer going to sleep or hibernating in the Power Settings.
	Windows also has a mode called "Connected Standby" which is not Sleep mode and is not fully running. It is used on laptops and tablets. It shuts off audio in that mode. It is trying to save you battery power, but it gives no easy option to leave the audio running.



	ragistry as follows:
	registry as follows:
	Tap on the Windows-key, type regedit.exe and hit the Enter-key. Navigate to the key: HKEY_LOCAL_MACHINE\SYSTEM\CurrentControlSet\Control\Power Locate the preference CsEnabled on the right side. Double-click on it, and set its value to 0. Restart the PC.
	A negative effect of this is that it may take longer for your device to wake up, which impacts when the device is ready for use.
The Frequency Spectrum is truncated in IQ mode	Even though you may have set FoxTelem to the
and only seems to show the middle part. See	right sample rate (e.g. 192000 or 96000) the audio
Figure 1.	source you are reading from is supplying audio at
	a lower rate. Figure 1 shows FoxTelem expecting
	samples at 192000 and receiving samples at 48000.
I connect to my computer using a Remote	This seems to be a Windows "feature". When
Desktop Connection (RDP) and FoxTelem is	you connect the RDP connection kills something
always not running.	in the audio subsystem that upsets Java. This is
	outside the FoxTelem code base and I don't have
	a fix. I recommend using AnyDesk for remote
	connections.

Figure 1: Too narrow a bandwidth on audio device used for IQ source

